STORAGE DEVELOPER CONFERENCE



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# Computational Storage APIs

Oscar P Pinto, Principal Engineer Samsung Semiconductor Inc.

#### Agenda

- Overview
- Introducing CS APIs
- API Usage by Example
- Example in Code
- Advanced Topics
- Summary

## **Computational Storage**

Why an API Library?



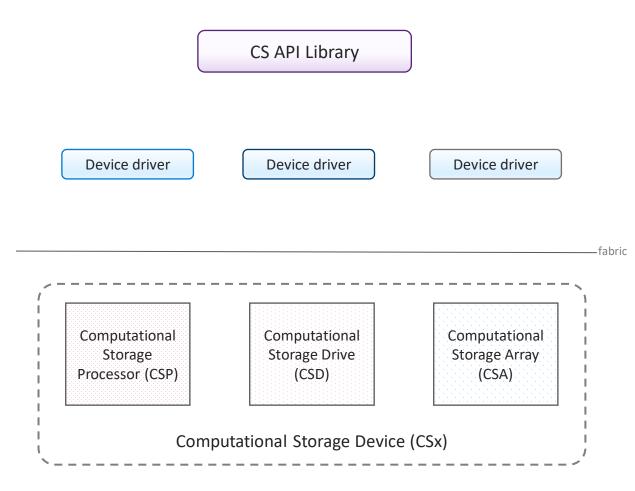
#### Why Computational Storage?

- Data is being created at a exponential rate
- Storage has also grown to account for this growth
- NVMe SSDs provide better performance than ever before
  - But their bandwidth not fully utilized by Host
- General purpose CPUs not able to fully tap this bandwidth
  - Scaling limited by PCIe lanes
- SSDs have more internal bandwidth than utilized
- Computational Storage & Offloads tap into this
  - Process data near storage
  - Add compute to storage



#### **CS API Library Overview**

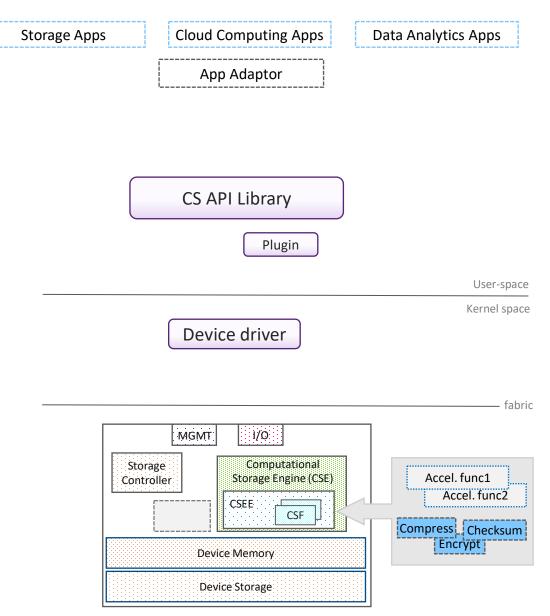
- One Set of APIs across all CSx types
  - CSP, CSD, CSA
  - Common set of APIs for different CS devices
- One interface to different device and connectivity choices
  - Hardware ASIC, CPU, FPGA, etc
  - NVMe/NVMe-oF, PCIe, custom, etc
- Configurations may be local/remote attached
- Hides vendor specific implementation details below library
- Abstracts device specific details
- APIs to be OS agnostic





#### About API Library

- Uniform interface for multiple configurations
  - APIs provided in common library
- Each CSx managed through its own device stack
  - Library may interface with additional plugins based on implementation requirements
  - Plugins help connect CSx to abstracted CS interfaces
- Extensible Interface
- CS APIs abstract
  - Discovery
  - Device Access
  - Device Memory (mapped/unmapped)
  - Near Storage Access
  - Copy Device Memory
  - Download CSFs
  - Execute CSFs
  - Device Management

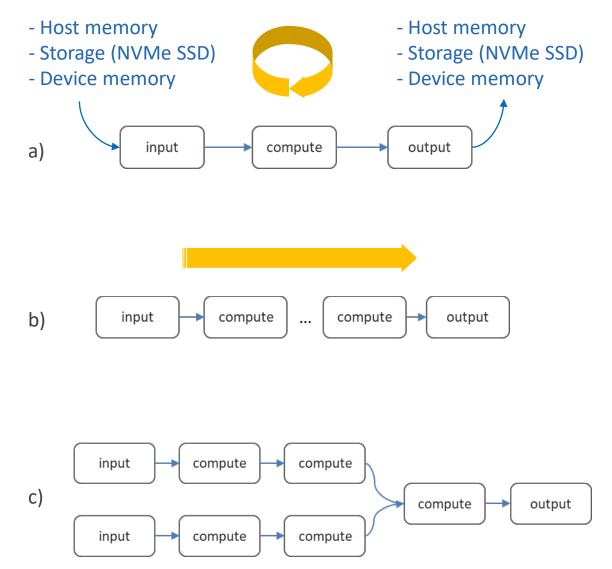


Computational Storage Drive (CSD)



#### **API Requirements**

- One interface across CS devices
  - CSDs, CSPs, CSAs
- Discovery
- Access
- Configure
- Device Memory Allocation
- Data Movement
  - Input: Host memory, Storage, Device memory
  - Output: Device memory, Storage, Host memory
- Execute
- Device Management
- Queued I/O Requests
- Transparent Local/Remote usages
- Security



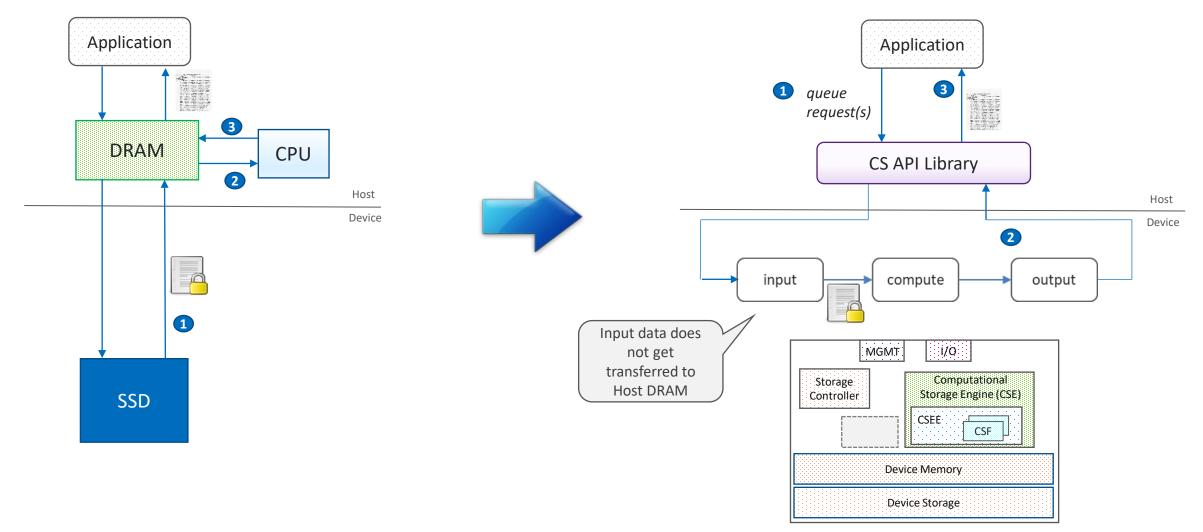


## How to use Computational Storage

Usage by example



#### **Applying Computational Storage**



Computational Storage Drive (CSD)



## Computational Storage API Details



#### **Discovery & Access APIs**

CS\_STATUS **csGetCSxFromPath**(char \*Path, unsigned int \*Length, char \*DevName); CS\_STATUS **csQueryFunctionList**(char \*Path, unsigned int \*Length, char \*Buffer);

CS\_STATUS **csOpenCSx**(char \*DevName, void \*DevContext, CS\_DEV\_HANDLE \*DevHandle); CS\_STATUS **csCloseCSx**(CS\_DEV\_HANDLE DevHandle);

CS\_STATUS csGetFunction(CS\_DEV\_HANDLE DevHandle, char \*Name, void \*Context, CS\_FUNCTION\_ID \*FunctionId);

#### Discovery

- Discover CSx devices
  - By device path, file/directory path or all
- Discover CSFs by requirement

#### Access

- Access CSx once discovered for CS usage
- Get access to a specific CSF for execution

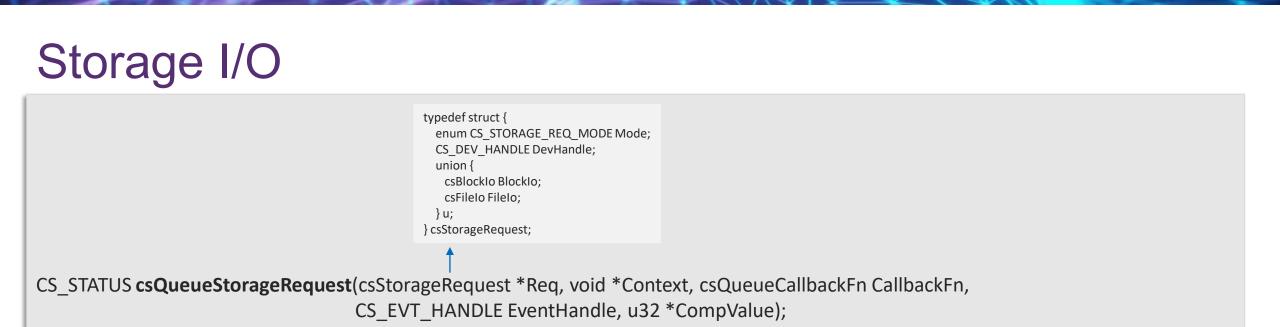


#### **Device Memory**

CS\_STATUS **csAllocMem**(CS\_DEV\_HANDLE DevHandle, int Bytes, unsigned int MemFlags, CS\_MEM\_HANDLE \*MemHandle, CS\_MEM\_PTR \*VAddressPtr); CS\_STATUS **csFreeMem**(CS\_MEM\_HANDLE MemHandle);

- Allocate / Deallocate Device Memory
- Manage Device Memory
  - Memory scheme
    - Memory mapped (PCIe BAR)
    - Opaque
  - Memory organization
    - Host managed
    - Device managed
- Mapping of memory to application space depends on the device
- Transparent to fabric usages
- Returns memory handle
  - Virtual address pointer when applicable





- Initiate direct internal transfers between storage (SSD) and allocated Device Memory
  - Seamlessly manages mapped/unmapped device memory
  - P2P transfers through file system if device supports memory mapped P2P BAR
- Single interface to support block & file; extensible
- Transparent to fabric usages
- Follows common completion modes
  - Synchronous
  - Asynchronous callback
  - Asynchronous event

Some modes not available in all configurations



- Initiate execution of a CSF with its input and output parameters
- API extensible for parameters
- Transparent to fabric usages
- Follows common completion modes
  - Synchronous
  - Asynchronous callback
  - Asynchronous event

Some modes not available in all configurations

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#### **Copy Device Memory**



Transfer data between Host memory and allocated Device Memory

#### Single interface for transfer operations

- Transparent to fabric usages
- Follows common completion modes
- Common completion modes
  - Synchronous
  - Asynchronous callback
  - Asynchronous event

Some modes not available in all configurations

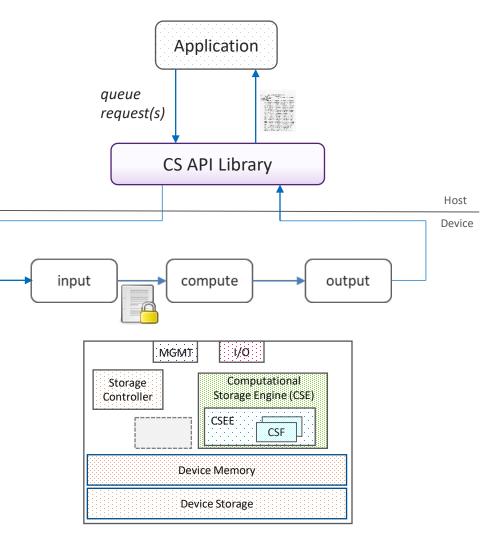
## Coding the Example

Applying APIs to example



#### **APIs Required for Example**

- 1. Discover CSx & CSF
- 2. Allocate Device Memory
- 3. Queue Storage Request
- 4. Queue Compute Request
- 5. Queue Copy Memory Request



Computational Storage Drive (CSD)



#### Sample Code – Decrypt file

#include <cs.h> int cs decode (char \*file path, int fd, void \*decode buf) // discover my CS device (CSx) and CSF (1)length = sizeof(csxBuffer); status = csGetCSxFromPath(file path, &length, &csxBuffer); status = csOpenCSx(csxBuffer, &MyDevContext, &devHandle); status = csGetFunction(devHandle, myFunction, NULL, &functId); // allocate device memory for input and output buffers (2)status = csAllocMem(devHandle, CHUNK SIZE, 0, &inMemHandle, NULL); status = csAllocMem(devHandle, CHUNK SIZE, 0, &outMemHandle, NULL); // allocate storage request & read chunk size data from file handle fd 3 storReq = calloc(1, sizeof(CsStorageRequest)); if (!storReq) { ERROR OUT("memory alloc error\n"); } storReq->Mode = CS STORAGE FILE IO; storReq->DevHandle = devHandle; storReq->u.CsFileIo.Type = CS STORAGE LOAD TYPE; storReq->u.CsFileIo.FileHandle = fd; storReg->u.CsFileIo.Offset = 0; storReq->u.CsFileIo.Bytes = CHUNK SIZE; storReq->u.CsFileIo.DevMem.MemHandle = inMemHandle; storReq->u.CsFileIo.DevMem.ByteOffset = 0; status = csQueueStorageRequest(storReq, storReq, NULL, NULL);

{

// allocate compute request for 3 args & issue compute request compReg = calloc(1, sizeof(CsComputeRequest) + (sizeof(CsComputeArg) \* 3)); if (!compReq) { ERROR OUT("memory alloc error\n"); } compReq->DevHandle = devHandle; compReq->FunctionId = functId; compReq->NumArgs = 3;argPtr = &compReq->Args[0]; csHelperSetComputeArg(&argPtr[0], CS AFDM TYPE, inMemHandle, 0); csHelperSetComputeArg(&argPtr[1], CS 32BIT VALUE TYPE, CHUNK SIZE); csHelperSetComputeArg(&argPtr[2], CS AFDM TYPE, outMemHandle, 0); status = csQueueComputeRequest(compReq, NULL, NULL, NULL, NULL); // allocate copy request & copy results to host buffer copyReg = calloc(1, sizeof(CsCopyMemRequest)); if (!copyReq) { ERROR OUT("memory alloc error\n"); } copyReq->Type = CS COPY FROM DEVICE; copyReq->HostVAddress = decode buf; copyReq->DevMem.MemHandle = outMemHandle; copyReq->DevMem.ByteOffset = 0; copyReq->Bytes = CHUNK SIZE;

status = csQueueCopyMemRequest(copyReq, NULL, NULL, NULL, NULL);

return 0;

\*API return status values are not shown to check for success and errors to ease readability



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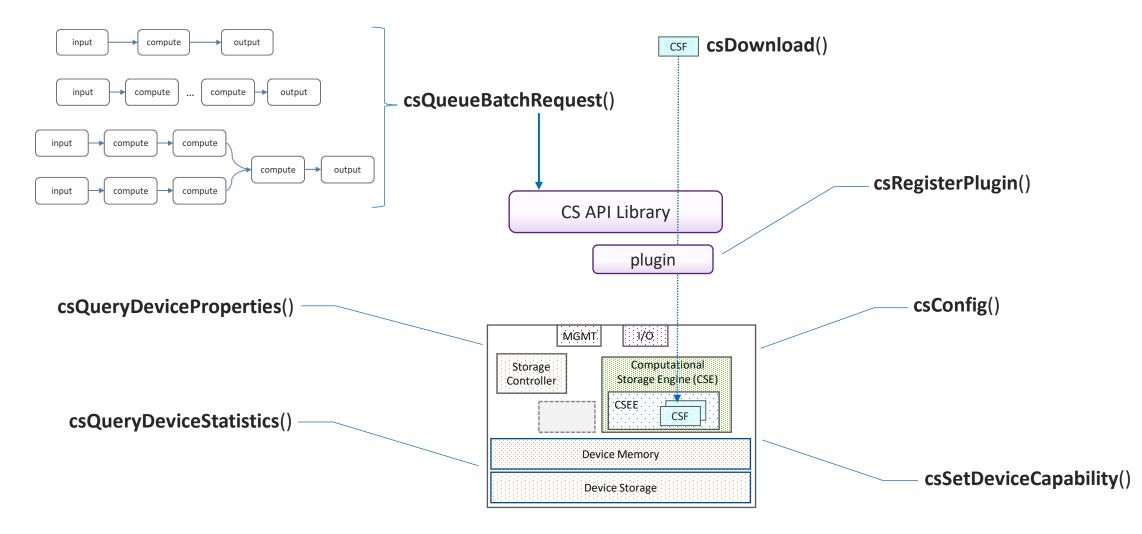
This presentation discusses SNIA work in progress, which is subject to change without notice

### Other APIs

What else can the APIs do?



#### **Other Interfaces**





#### **Call for Action**

#### Other sessions on Computational Storage

- Samsung Keynote Yang Seok Ki
- Moving forward with an Architecture & API Bill Martin
- Computational Storage Update from SNIA WG Scott Shadley & Jason Molgaard
- NVMe Computational Storage Update Kim Malone & Stephen Bates

#### Join the standardization efforts

- SNIA, NVMe
- Help build the ecosystem



## Thank You





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