A SNIA. Event

STORAGE DEVELOPER CONFERENCE



BY Developers FOR Developers

The Path to Autonomous Storage is Broken

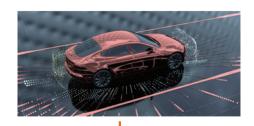
Presented by Eric Wright (@DiscoPosse)
Technology Advocate, Magnition.io

What is preventing the industry from achieving fully autonomous storage?



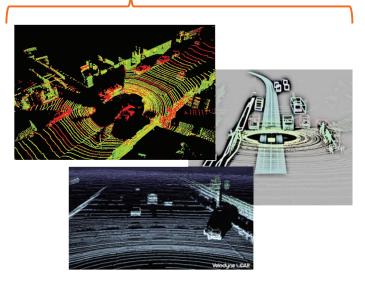
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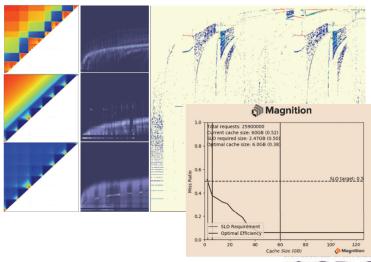




Multi-Dimensional Challenges







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Manual Storage / Memory Management Now Infeasible

Applications and data requirements changing hourly





Increasing hardware complexity

Manually-managed Storage / Memory Infrastructure

Vulnerable to:

- Thrashing, Scan pollution
- Gross unfairness, Interference
- Unpredictable availability
- Data loss risks

- \Rightarrow Overprovisioning
- ⇒ Lack of Control
- ⇒ Availability & Durability Risk





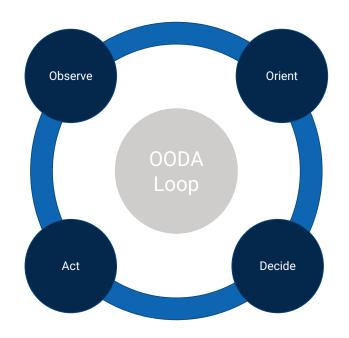




How do we cross the chasm to fully autonomous storage and memory hierarchies?



Autonomous Systems Require OODA Loops & Models





Autonomous Storage ML/Models Needed



Self-Awareness

Acceleration, braking steering, roll, wear/tear, weight distribution, battery discharge temperature and load models

Environment Awareness

Maps, static obstacles, dynamic obstacles, object capabilities, terrain, distances, relative object velocities, live traffic, GPS, road conditions, weather, law enforcement, etc.



Self-Awareness

Caches, memories, disks, data paths, latencies, link throughput limitations, media costs, data movement costs, performance capabilities, degraded performance, etc.

Environment Awareness

Dynamic workloads, QoS constraints, competing traffic on links, dynamic laaS costs, failures, imminent failures, flash wear/tear, power constraints, temperature, dynamic resource costs, etc.





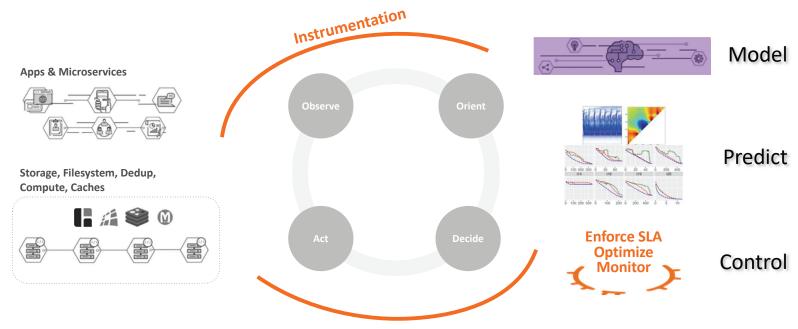
Autonomous Levels



Admin controls the storage device; device can detect and send alerts, etc.	Level 1 Operator Assistance	Driver controls the car; car can alert driver to conditions, obstructions, etc.
Automated failure repair, backup, replication, recovery; Admin remains engaged	Level 2 Partial Automation	Automated acceleration, steering; Driver remains engaged
Device manages many cost / performance tradeoffs; Admin must be ready to take over	Level 3 Conditional Automation	Car manages most safety driving functions; Driver must be ready to take control
Device guarantees QoS constraints at lowest cost, is self-aware, self-troubleshooting; Admin has option to control	Level 4 High Automation	Car capable of performing all safety-critical functions; driver has option to control
Device is completely lights-out, hands-off, no control UI, only high-level policy controls; Admin install spares when instructed	Level 5 Fully Autonomous	Vehicle completely driverless, no driving equipment (e.g. steering)



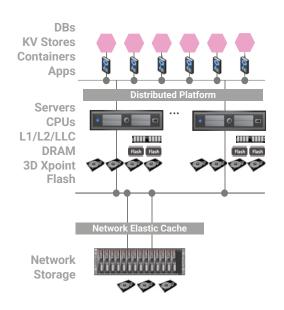
Architecture for Fully Autonomous Storage



Auto-tune, Auto Size, Reconfigure, QoS Control



Fully Autonomous Storage / Memories are Self-Aware



Fully Autonomous Storage Needs Must Continuously Answer

- · Is this performance good?
- Can performance be improved?
- How much Cache for App A vs B vs ...?
- What happens if I add / remove DRAM?
- · How much DRAM versus Flash?
- How to achieve 99%ile latency of X μs?
- · What if I add / remove workloads?
- Is there cache thrashing / pollution?
- · What if I change cache parameters?



Use Case #1: Autonomous QoS SLA

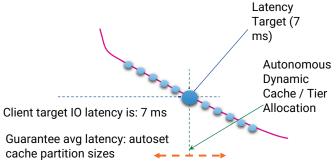
How?

- Users dial-in latency or throughput target and budgets
- Fully Autonomous Storage auto allocates just enough capacity to meet SLAs at all times

Value for Customer

- Automated SLA achievement!
- · Set and Forget, ease of mind
- · Revenue disruption avoidance
- Improved margins
- Zero OpEx performance scaling
- Dramatically reduced service interruptions

Latency Guarantees





Use Case #2: Autonomous Cost / Performance Optimization

How?

- · Real-time workload modeling
- · Resource allocation predictions
- Dynamic resource adjustment and isolation
- · Auto right-sizing

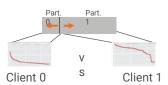
Value for Customer

- Lowest total cost of ownership (TCO)
- Eliminate noisy neighbor problems
- Policy-driven operations
- Lower OpEx for infra teams
- · Predictive planning

Cache Size & Latency Reduction (Thrashing Remediation)



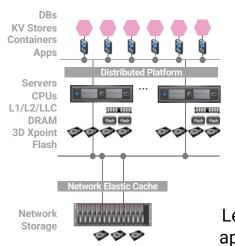
Tenant Isolation





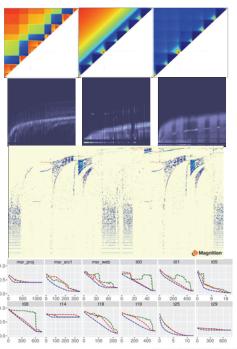


Modeling Storage Performance in Real-Time





Learn performance model of applications and storage system
Predict the performance of workload as f(resources, params)



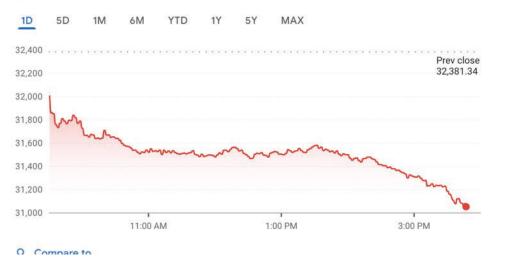


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Dow Jones Industrial Average

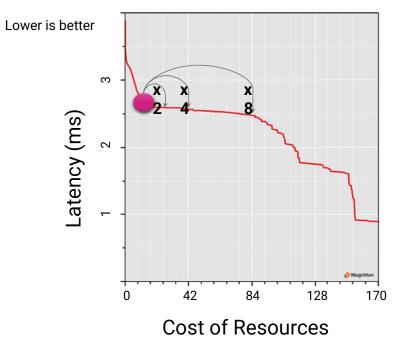
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Understanding Autonomous Performance Models



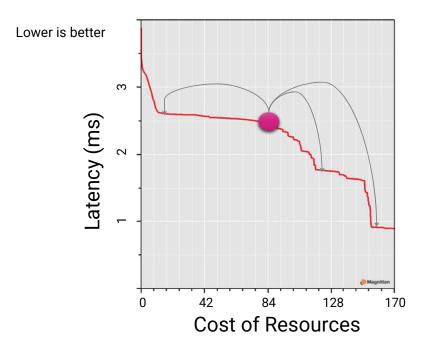
Models help decide useful increments of change.

In this example, no benefit despite an 8x increase in budget.



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Understanding Autonomous Performance Models



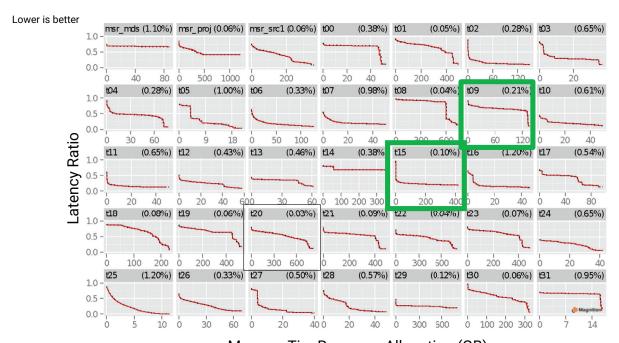
Often, most operating points are highly inefficient.

This system is operating at the lowest ROI point; equivalent performance to 1/8 the budget.

Autonomous memory hierarchies should pick efficient operating points.



Sample Models For Production Applications

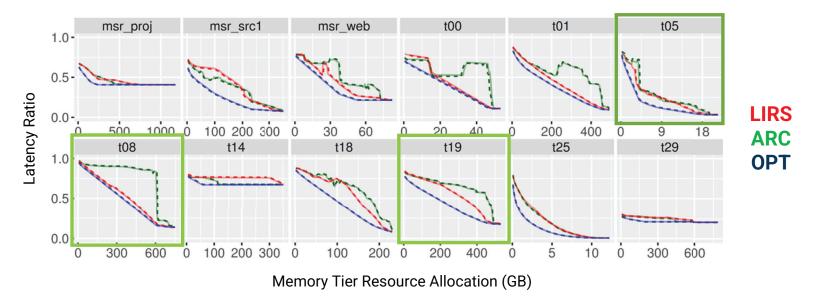


Memory Tier Resource Allocation (GB)



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Production Applications with Different Performance Policies



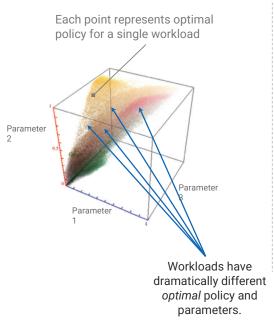


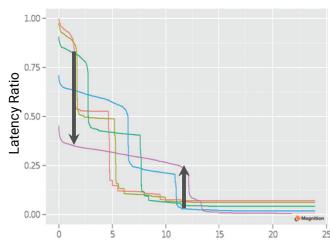




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Understanding Fully Autonomous Adaptation





Same Workload. Real-time Performance Prediction under different policies.

Autonomous memory hierarchies would always pick the optimal operating parameters.

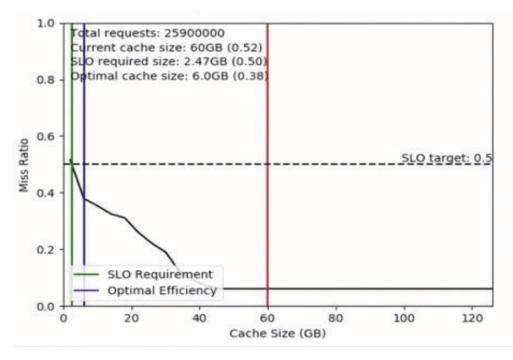
arameters.

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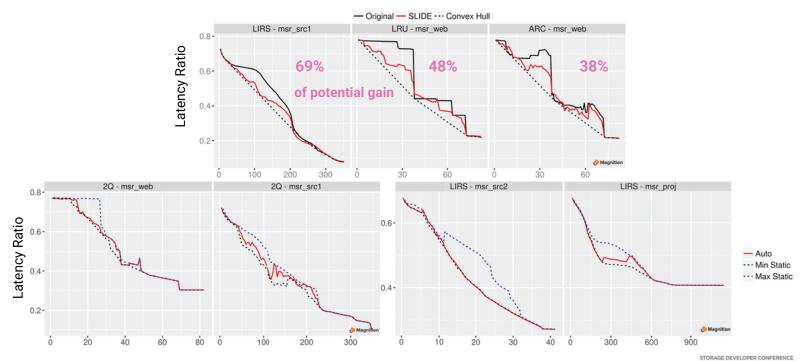
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From CacheLab to Autonomous Storage



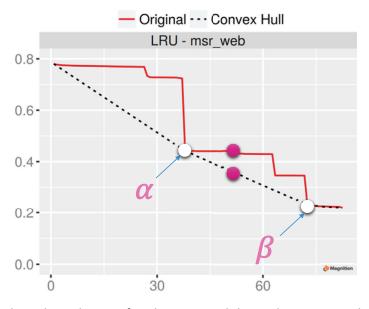


Fully Autonomous Storage is Self-Adaptive



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Fully Autonomous Performance Optimizations



Thrash remediation algorithm

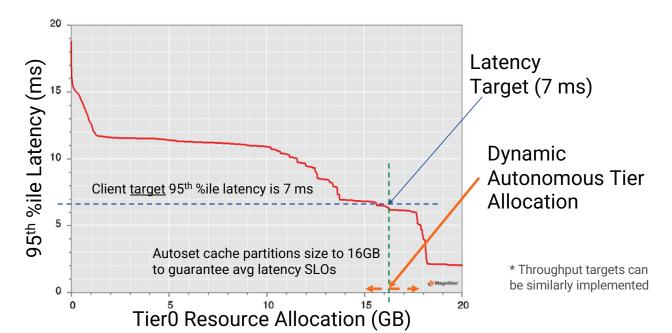
Convex hull interpolation Curve steering

Optimal curve bending cache-unfriendly workloads

hash-based emulation of cache sizes and depend on statistical self-similarity

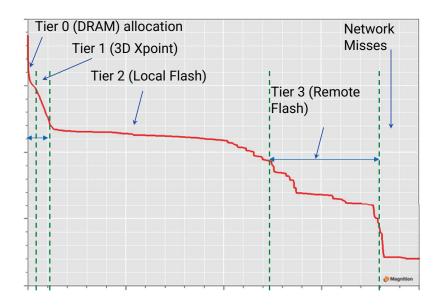


Fully Autonomous Latency Targets



SD€

Fully Autonomous Multi-Tier Allocation



* Can model network bandwidth as a function of cache misses from each tier





Implement a custom evacuation algorithm

Use CacheLab to prove your algorithm is better



Fully Autonomous Storage is Within Reach



This is you



This should be your customer





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