

# Storage Lessons from HPC Extreme Scale Computing Driving High Performance Data Storage

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### **Abstract**



- In this tutorial, we will introduce the audience to the lunatic fringe of extreme high-performance computing and its storage systems. The most difficult challenge in HPC storage is caused by millions (soon to be billions) of simultaneously writing threads. Although cloud providers handle workloads of comparable, or larger, aggregate scale, the HPC challenge is unique because the concurrent writers are modifying shared data.
- ➤ We will begin with a brief history of HPC computing covering the previous few decades, bringing us into the petaflop era which started in 2009. Then we will discuss the unique computational science in HPC so that the audience can understand the unavoidability of its unique storage challenges. We will then move into a discussion of archival storage and the hardware and software technologies needed to store today's exabytes of data forever. From archive we will move into the parallel file systems of today and will end the lecture portion of the tutorial with a discussion of anticipated HPC storage systems of tomorrow. Of particular focus will be namespaces handling concurrent modifications to billions of entries as this is what we believe will be the largest challenge in the exascale era.

### **Eight Decades of Production Weapons** Computing to Keep the Nation Safe

















SGI Blue Mountain

DEC/HP Q

IBM Cell Roadrunner











Ising DWave

Cross Roads



Cray Intel KNL Trinity

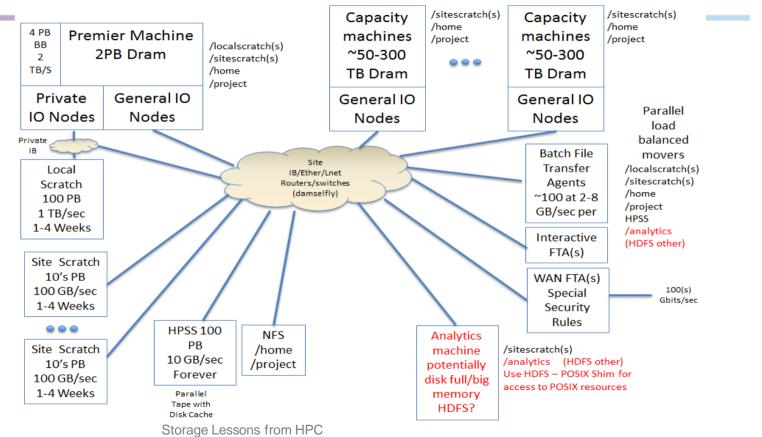






# Simple View of our Computing Environment







### **Large Machines and Infrastructure**



### **Trinity**

- Haswell and KNL
- → 20,000 Nodes
- Few Million Cores
- 2 PByte DRAM
- 4 PByte NAND Burst Buffer
  - ~ 4 Tbyte/sec
- 100 Pbyte Scratch PMR Disk File system
  - ~1.2 Tbyte/sec
- 30PByte/year Sitewide SMR Disk Campaign Store
  - ~ 1 Gbyte/sec/Pbyte (30 Gbyte/sec currently)
- 60 PByte Sitewide Parallel Tape Archive
  - ~ 3 Gbyte/sec



### Pipes for Trinity Cooling

- 30-60MW
- Single machines in the 10k nodes and > 18 MW
- Single jobs that run across IM cores for months
- Soccer fields of gear in 3 buildings
- 20 Semi's of gear this summer alone

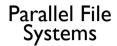


# **HPC Driving Industry**



















#### Parallel **Archives**







Other





Data

Warp Storage Lessons from HPC

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### Ceph begins

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SANTA BARBARA • SANTA

DEPARTMENT OF COMPUTER SCIENCE

SANTA CRUZ, CALIFORNIA 95064

April 8, 2001

Lawrence Livermore National Laboratory Attention: Barbara Larson, L-550 P.O. Box 808 Livermore, CA 94551

Dear Ms. Larson.

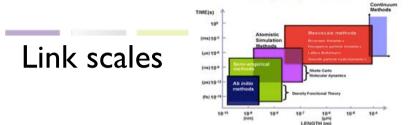
We are pleased to submit this white paper to the ASCI ASAP Request for Expressions of Interest in Level 2 Strategic Investigations. We are responding to the Scalable and Parallel I/O and File Systems area of interest.

We propose to improve both file system performance and functionality by building a storage system from object-based storage devices (OBSDs) connected by high-speed networks. The key advantage of OBSDs in a high-performance environment is the ability to delegate low-level block allocation and synchronization for a given segment of data to the device on which it is stored, leaving the file system to decide only on which OBSD a given segment should be placed. Since this decision is quite simple and allows massive parallelism, each OBSD need only manage concurrency locally, allowing a file system built from thousands of OBSDs to achieve massively parallel data transfers. Additionally, OBSDs can each manage their own storage consistency, removing the need to run a system-wide consistency check that could take days on a petabyte-scale traditional file system.

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### HPC Simulation Background



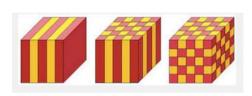


http://eng-cs.syr.edu/research/mathematical-and-numerical-analysis

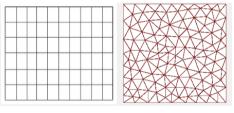
1D 2D 3D

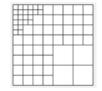
**Hierarchy of Computer Simulations** 

Meshes



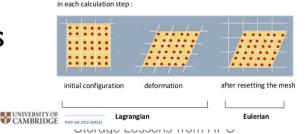
#### Structured Unstructured Resolutions



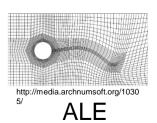


### Lagrangian Eulerian

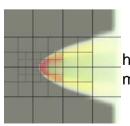
**Methods** 



### **ALE**



### **AMR**



http://web.cs.ucdavis.edu/~ ma/VolVis/amr\_mesh.jpg

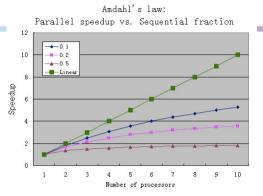
**Eulerian AMR** 

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### **Scaling and Programming**

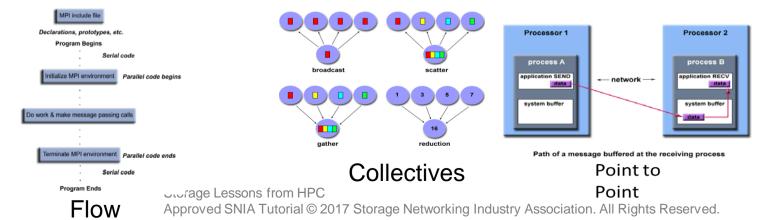






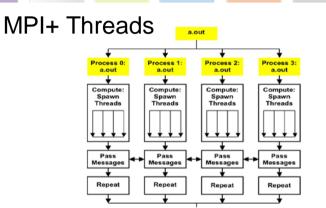
Strong scaling: fixed total problem size Weak scaling: fixed work per task

### Process Parallel Dominates the Past

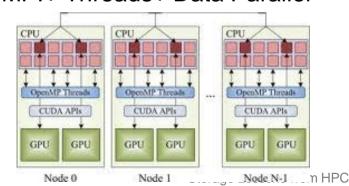


### **Current Programming Model Directions** Combining Process Parallel, Data Parallel, Async Tasking, and Threading SNIA



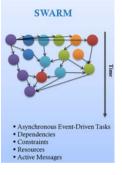


MPI+ Threads+ Data Parallel



MPI+Data Parallel Host (CPU) Host (CPU)

Async Tasking



Domain Specific Languages

Others: OpenShmem, CAF, Chapel, X10 are possible as well



# Workflow Taxonomy from APEX Procurement A Simulation Pipeline



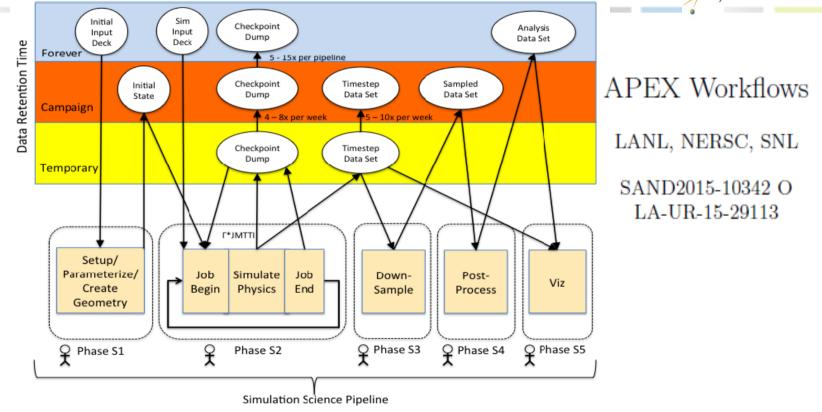
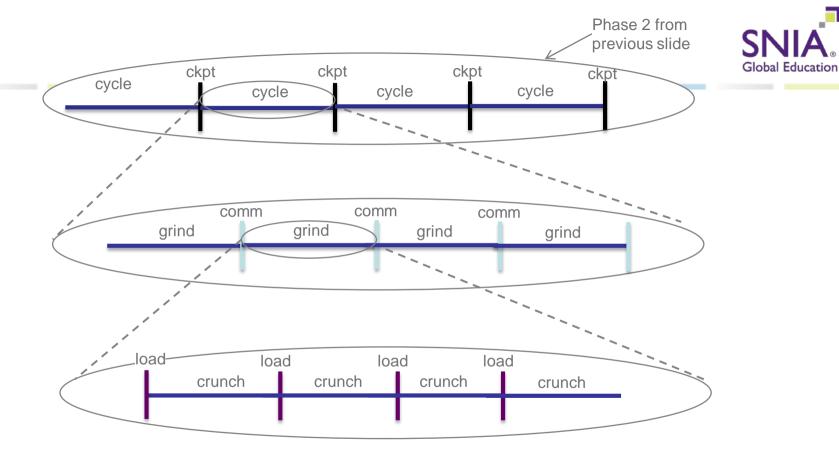


Figure 1: An example of an APEX simulation science workflow.

leserved.



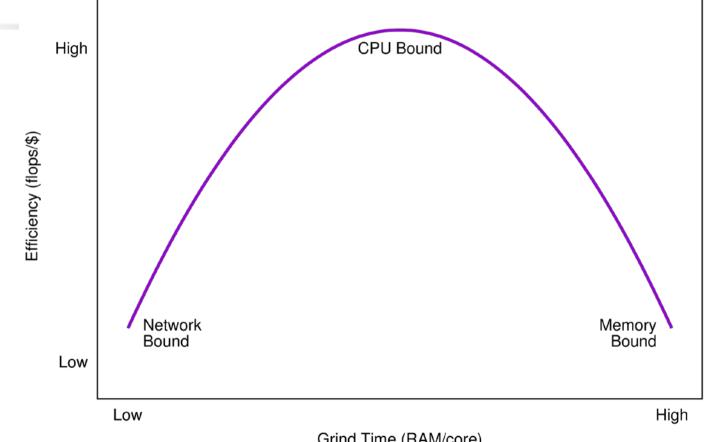
Key observation: a grind (for strong-scaling apps) traverses all of memory.

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#### Balancing Flops and RAM





Grind Time (RAM/core)
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## **Not Just Computation**



failure

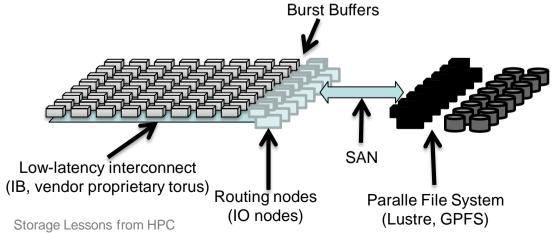


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### **HPC** environment



→ Big difference from cloud: parallel, tightly coupled, extremely simple nodes to lower jitter and job failure due to tightly coupled behavior (one code syncs between all neighbors every 1 millisecond [comm of grind crunch])



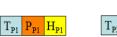
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### **HPC IO Patterns**

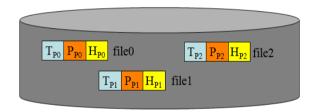


#### N-to-N

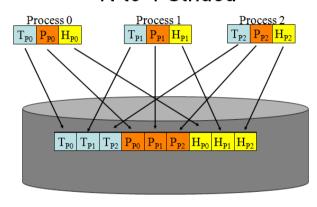
Process 1







#### N-to-1 Strided



- Million files inserted into a single directory at the same time
- Millions of writers into the same file at the same time
- Jobs from 1 core to N-Million cores
- Files from 0 bytes to N-Pbytes

 $P_{p_0} | H_{p_0}$ 

Process 0

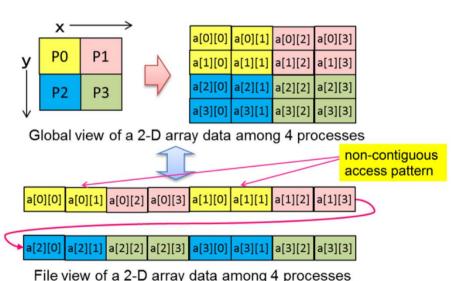
Workflows from hours to a year (yes a year on a million cores using a PB DRAM)

# A Simple collective 2D layout as an example

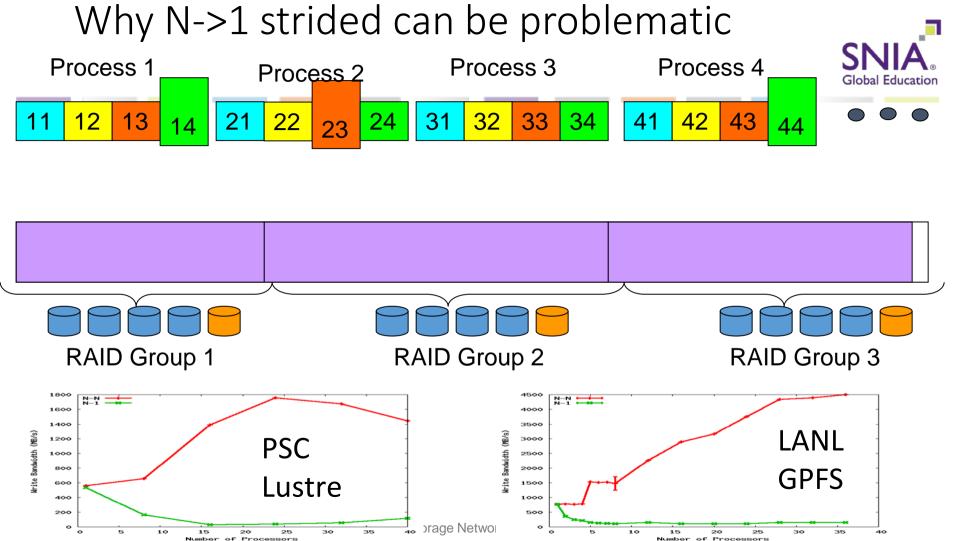


#### Collective I/O for 2-Dimensional Data

• 2-Dimensional data accesses by 4 processes



Apps can map their 1,2,3,N dimensional data onto files in any way they think will help them This leads to formatting middleware like HDF5, NetCDF, MPI-IO



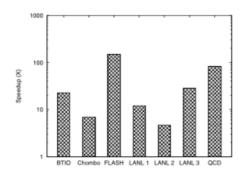


# PLFS: A Checkpoint Filesystem for Parallel Applications

John Bent<sup>\*</sup>; Garth Gibson<sup>‡</sup>; Gary Grider<sup>‡</sup>; Ben McClelland<sup>‡</sup>; Paul Nowoczynski<sup>‡</sup>; James Nunez<sup>‡</sup>; Milo Polte<sup>‡</sup>; Meghan Wingate<sup>\*</sup>

#### ABSTRACT

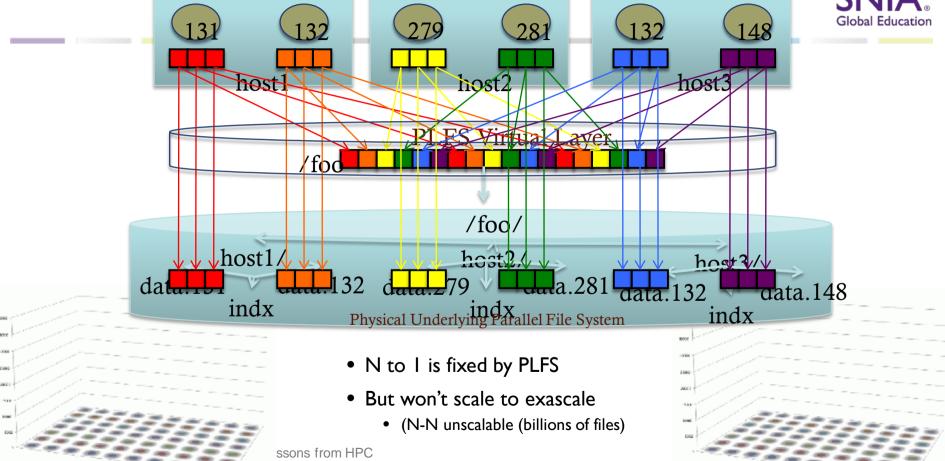
Parallel applications running across thousands of processors must protect themselves from inevitable system failures. Many applications insulate themselves from failures by checkpointing. For many applications, checkpointing into a shared single file is most convenient. With such an approach, the size of writes are often small and not aligned with file system boundaries. Unfortunately for these applications, this preferred data layout results in pathologically poor performance from the underlying file system which is optimized for large, aligned writes to non-shared files. To address this fundamental mismatch, we have developed a virtual parallel log structured file system, PLFS, PLFS remaps an application's preferred data layout into one which is optimized for the underlying file system. Through testing on PanFS, Lustre, and GPFS, we have seen that this layer of indirection and reorganization can reduce checkpoint time by an order of magnitude for several important benchmarks and real applications without any application modification.



 Summary of our results. This graph summarizes our results which will be explained in detail in Section 4. The key observation here is that our technique has improved checkpoint bandwidths for all seven studied benchmarks and applications by up to several orders of magnitude.

**Decouples Logical from Physical** 

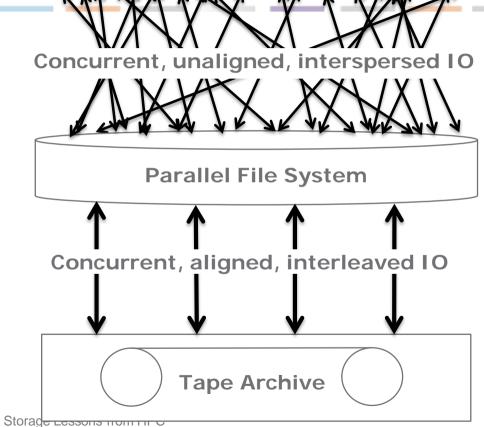




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### **Tightly Coupled Parallel Application**

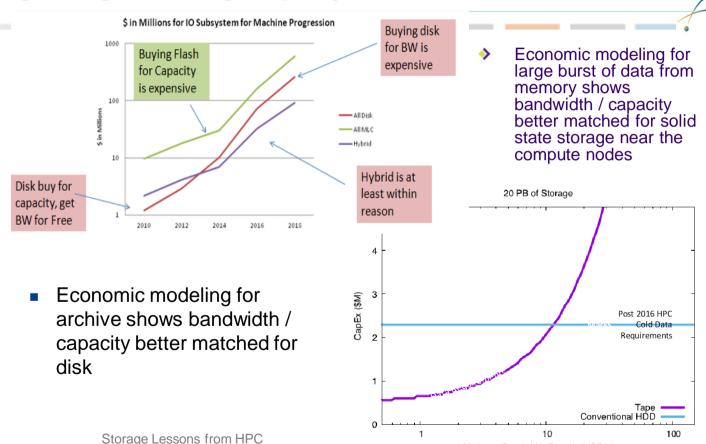




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# Economics have shaped our world The beginning of storage layer proliferation 2009

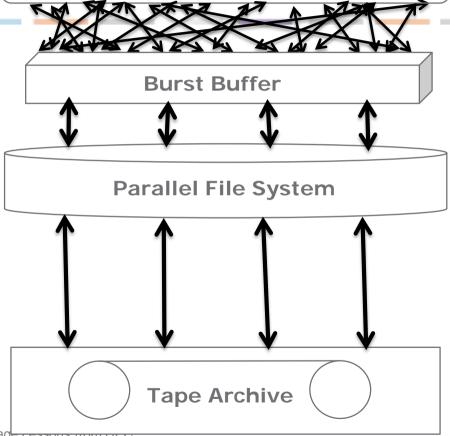




Minimum Bandwidth Required (GB/s)
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### **Tightly Coupled Parallel Application**

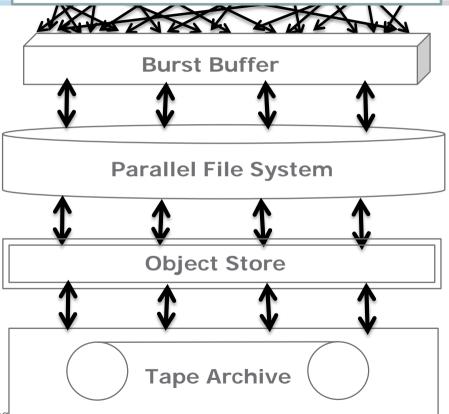




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# Tightly Coupled Parallel Application SCM





Storag<del>le Lessons nomme</del>

# simple story

why HBM?
CPU ←---→ DRAM



why SSD?

DRAM ←---→ HDD

why NVMe?

SCSI ←---→ SSD

why SMR?

HDD ←---→ Tape

why SCM?

DRAM ←---→ SSD

SSD exposed pent-up demand for storage IOPs and desire for finer and finer IOPs

why GenZ/OPA/etc?

NVMe ←---→ SCM

SSD exposed pent-up demand for shared IOPs to giant datasets

# which physical will survive? grider's bent crystal ball



### compute servers

hbm

scm

performance storage

dram

ssd

(performance hdd)

capacity storage

dram

capacity hdd



### how many logical tiers will survive?

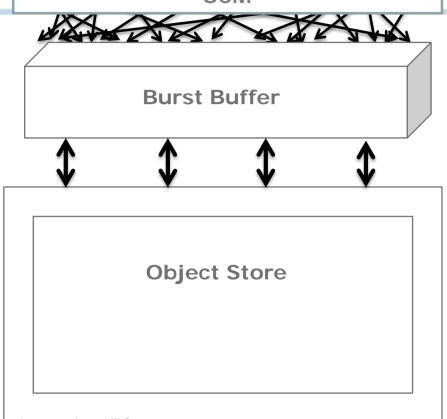
### the number is 2

of physical, there may be many
the number needed for economic efficiency
of logical, there should be two
the number needed to balance site, human, and workload efficiency

human in loop to make difficult decisions one storage system focused on performance, one on capacity capacity should be site-wide, performance can be machine-local better resilience, users should always have at least one available

# Tightly Coupled Parallel Application SCM





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# What about the Capacity Tier: Won't cloud technology provide the capacity solution?



- Erasure to utilize low cost hardware
- Object to enable massive scale
- Simple minded interface, get put delete
- → Problem solved --→ NOT
- Works great for apps that are newly written to use this interface
- Doesn't work well for people, people need folders and rename and ...
- Doesn't work for the \$trillions of apps out there that expect some modest name space capability (parts of POSIX)

# How about a Scalable Near-POSIX Name Space over Cloud style Object Erasure: MarFS



- Best of both worlds
  - Objects Systems
    - > Provide massive scaling and efficient erasure techniques
    - > Friendly to applications, not to people. People need a name space.
    - Huge Economic appeal (erasure enables use of inexpensive storage)
  - POSIX name space is powerful but has issues scaling
- The challenges
  - Mismatch of POSIX an Object metadata, security, read/write semantics, efficient object/file sizes.
  - No update in place with Objects
  - How do we scale POSIX name space to trillions of files/directories



### **MarFS**



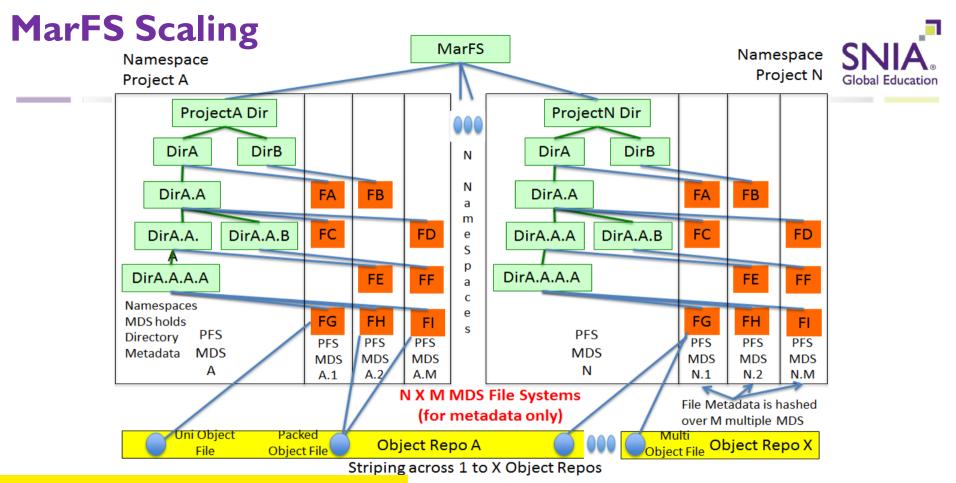
#### What it is

- ♦ 100-1000 GB/sec, Exabytes, Billion files in a directory, Trillions of files total
- Near-POSIX global scalable name space over many POSIX and non POSIX data repositories (Scalable object systems - CDMI, S3, etc.)
  - (Scality, EMC ECS, all the way to simple erasure over ZFS's)
- It is small amount of code (C/C++/Scripts)
  - A small Linux Fuse
  - A pretty small parallel batch copy/sync/compare/ utility
  - A moderate sized library both FUSE and the batch utilities call
- Data movement scales just like many scalable object systems
- Metadata scales like NxM POSIX name spaces both across the tree and within a single directory
- It is friendly to object systems by
  - Spreading very large files across many objects
  - Packing many small files into one large data object

#### What it isnt

No Update in place! Its not a pure file system, Overwrites are fine but no seeking and writing Storage Lessons from HPC

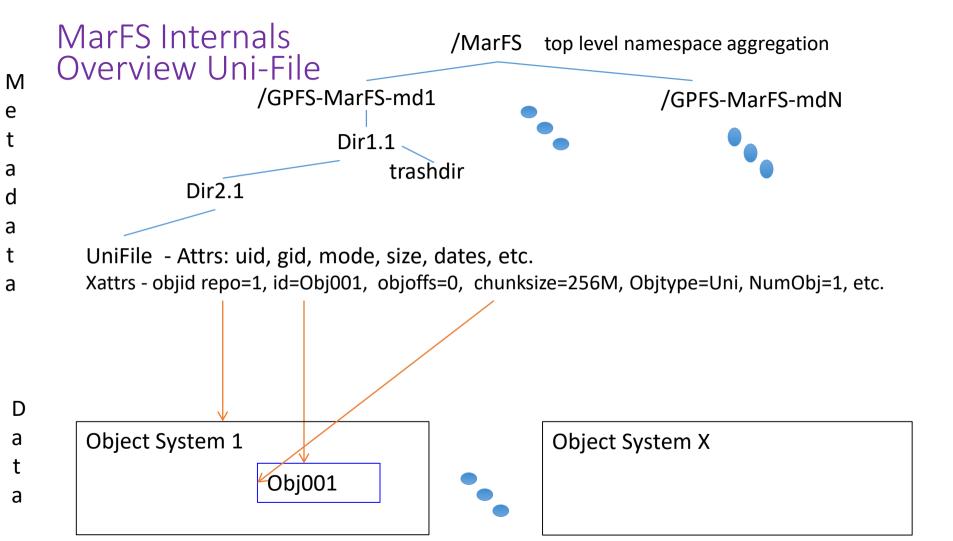


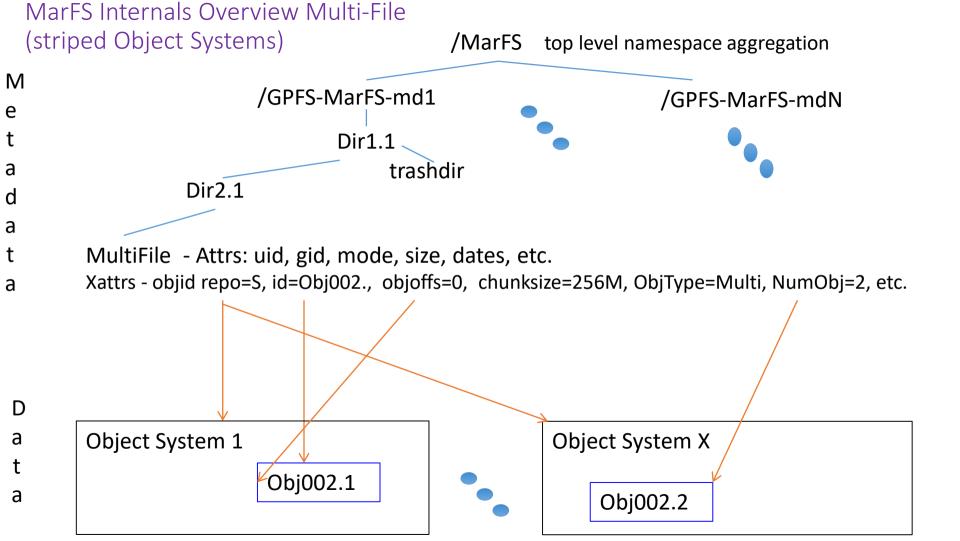


Scaling test on our retired Cielo machine: 835M File Inserts/sec Stat single file < 1 millisecond > 1 trillion files in the same director

Striping across 1 to X Object Repos

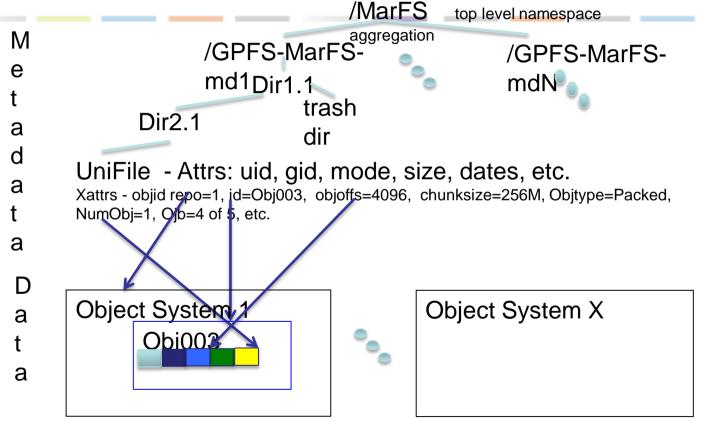
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### **MarFS Internals Overview Packed-File**



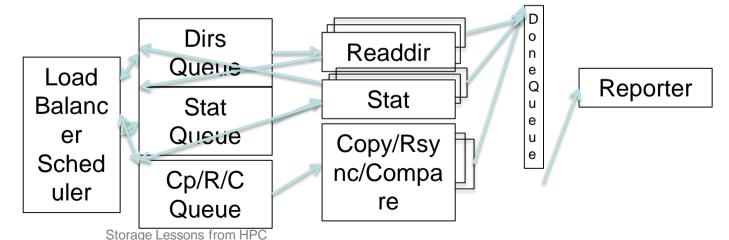


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# Pftool – parallel copy/rsync/compare/list tool

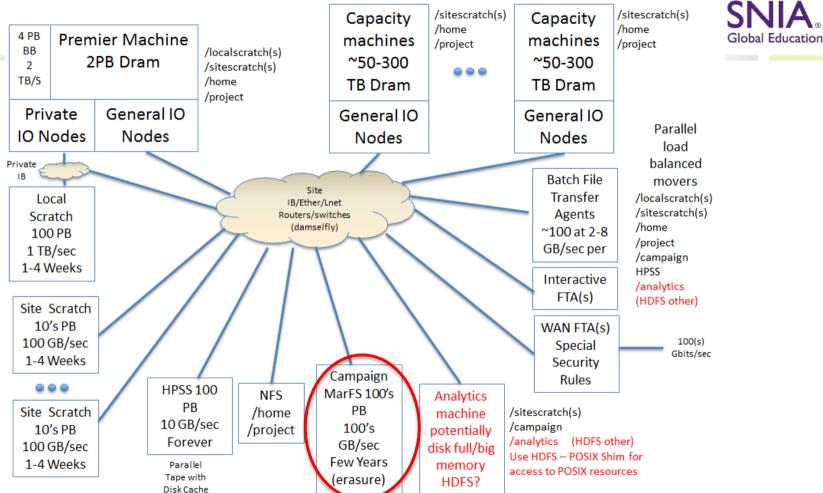


- Walks tree in parallel, copy/rsync/compare in parallel.
  - > Parallel Readdir's, stat's, and copy/rsinc/compare
  - Dynamic load balancing
  - Restart-ability for large trees or even very large files
  - Repackage: breaks up big files, coalesces small files
  - To/From NFS/POSIX/parallel FS/MarFS



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### How does it fit into our environment



### Not Just LANL Developing This Tier



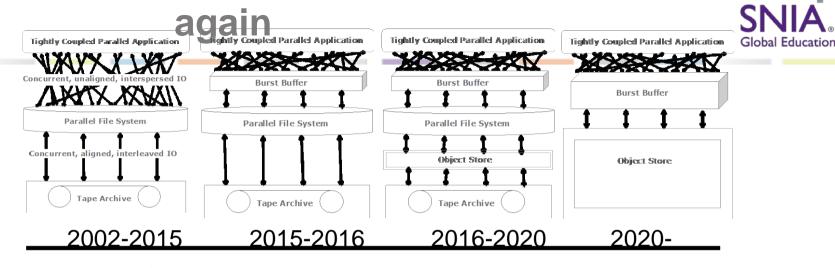




Seagate ClusterStor A200

#### Spectra Logic Campaign Storage LLC

### From 2 to 4 and back





#### Serving Data to the Lunatic Fringe: The Evolution of HPC Storage

;login: issue: Summer 2016, Vol. 41, No. 2

Authors:

John Bent, Brad Settlemyer, and Gary Grider

Article Section: STORAGE

Before the advent of Big Data, the largest storage systems in the world were found almost exclusively within high performance computing centers such as those found at US Department of Energy national laboratories. However, these systems are now dwarfed by large datacenters such as those run by Google and Amazon. Although HPC storage systems are no longer the largest in terms of total capacity, they do exhibit the largest degree of concurrent write access to shared data. In this article, we will explain why HPC applications must necessarily exhibit this degree of concurrency and the unique HPC storage architectures required to support them.



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### **DOE Exascale Computing and Future Considerations**



- R&D and integration required to deploy Applications on Exascale computers in 2023+
- Partnership involving: Government, Computer industry, DOE laboratorie, Academia
- Target System Characteristics
  - 1-10 Billion degrees of concurrency
  - 20-30 MW Power requirement for one machine (machine only)
  - <300 cabinets</p>
  - Development and execution time productivity improvements
  - 100 PB working sets
  - Checkpoint times < 1 minute ( constant failure)</li>
  - Storage systems need to be very reliable as the machine wont be
  - Leverage->Exploit new technology, dense flash/SCM/low latency high bandwidth byte addressable networks

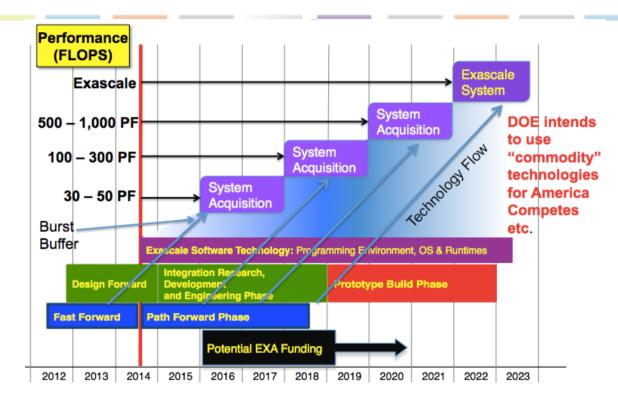






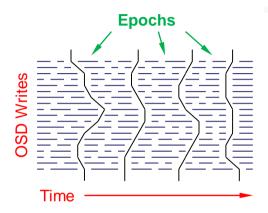
# **Exascale Computing Timeline**System Perspective





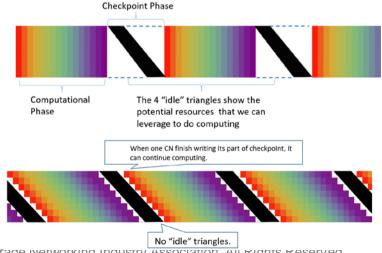
# Transactional/Versioning Coupled with Async Programming Models





Spread the load over as much time as the app will allow

### Save every microsecond



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# Exploiting New Techology (dense flash, SCM, one sided networks)



- Todays storage stacks do not allow full exploitation of even flash latencies never the less SCM – trapped IOP's in software
- Must move away from thin client to heavy server to block storage (Lustre, Ceph, MongoDB).
- These stacks are incredibly thick. Client KV/Object -> MDS/Access Server->KV/Object Server->Kernel File System->block or network block.
- Head towards embedding more of this in the client and provide light weight one side enabled servers.
- Applications use Middleware (HDF5 for example) to form Objects that go directly to light weight object servers, no real server just light weight kvs/object on the hardware.
  - HDF5 (HDF Group) Vol interface is an example
  - MDHIM (LANL) MultiDimensional Hierarchical Middleware is a user space distributed KVS middleware
  - DeltaFS (CMU/LANL) is a user space file system Middleware

# Open Source BSD License Partners Welcome



https://github.com/mar-file-system/marfs https://github.com/pftool/pftool)

Thank You For Your Attention







