SNIA | DATA, NETWORKING, DNSF | & STORAGE

Storage Requirements for Al

Training and Checkpointing

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The AI boom is driving incredible demand for GPUs leading to a need to maximize their utilization

GPUs Essential for Al

- Modern deep learning AI models require millions of matrix operations
- Matrix operations must be parallelized to make Al computationally feasible
- GPUs designed to do parallel matrix operations quickly and cost effectively.
- GPUs needed to make Al economically feasible

GPUs Expense and Scarce

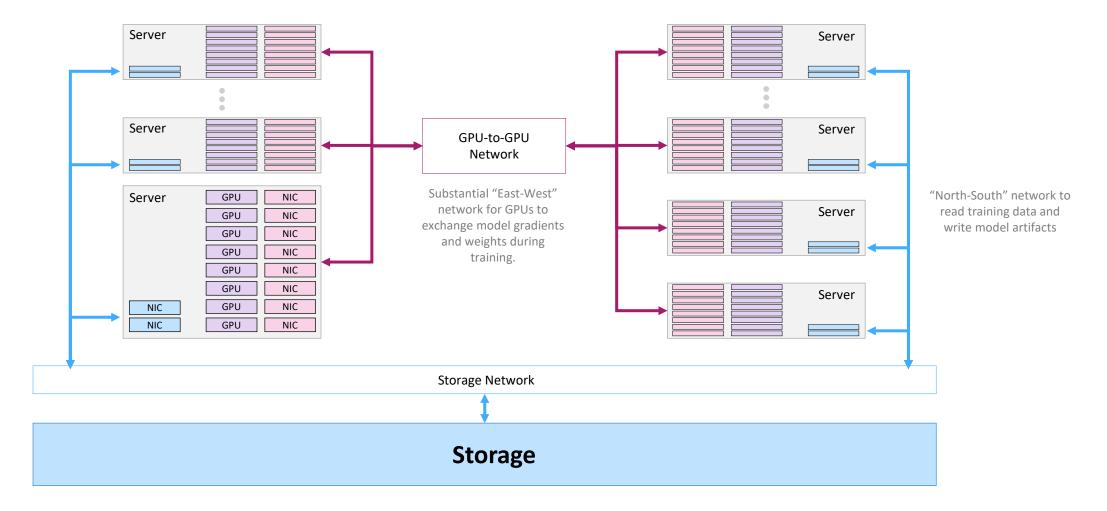
- Companies are racing to build AI datacenters
- Al datacenters can contain 100's to 1000's of GPUs
- Demand for GPUs is surpassing supply
- GPUs are becoming costly and difficult to acquire

Maximizing GPU Utilization Essential

- Demand, cost, and scarcity making GPUs the most valuable AI datacenter asset
- Companies must maximize the use of the GPUs they have
- *Maximizing GPU utilization* becoming the main AI datacenter design goal



Maximizing GPU utilization requires balancing compute, network, and storage performance



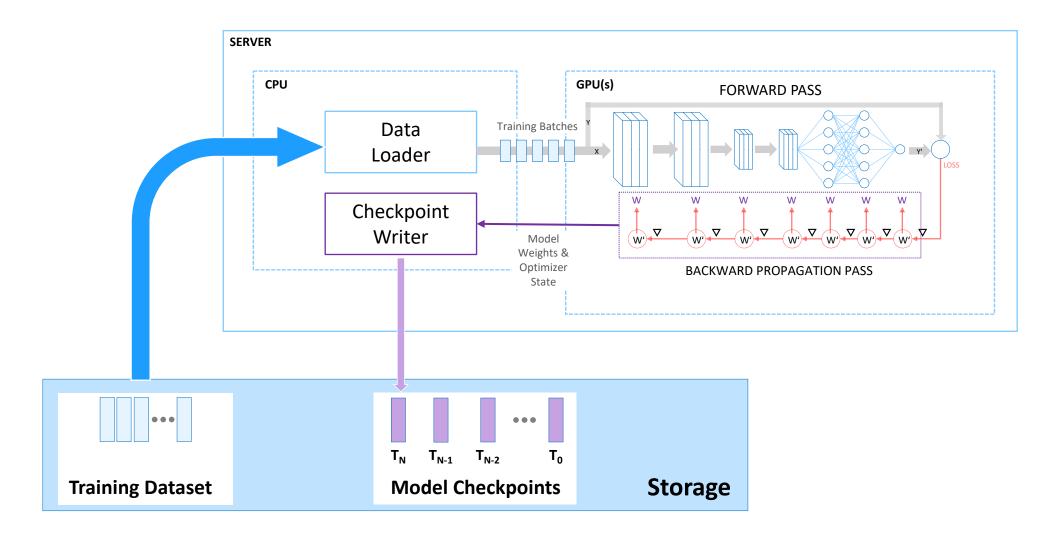


Storage plays an important role across entire Al lifecycle

Training & Tuning	Inference		
 Providing training data to keep expensive GPUs fully utilized Saving and restoring model checkpoints to protect training investments 	 Safely storing and quickly delivering model artifacts for inference services Providing data for batch inferencing 		
 Sustaining read bandwidths necessary to keep training GPU resources busy 	Reliably storing expensive to produce model artifact data		
 Minimizing time to save checkpoint data to limit training pauses 	 Minimizing model artifact read latency for quick inference deployment 		
 Scaling to meet demands of data parallel training in large clusters 	 Sustaining read bandwidths necessary to keep inference GPU resources busy 		
	 Providing training data to keep expensive GPUs fully utilized Saving and restoring model checkpoints to protect training investments Sustaining read bandwidths necessary to keep training GPU resources busy Minimizing time to save checkpoint data to limit training pauses Scaling to meet demands of data parallel 		



Al models trained using batches of training data to update model weights with periodic checkpoints for recovery





Limited information exists on training read performance requirements; GPU benchmarks provide a way to estimate



Run AI training benchmarks designed to saturate GPU utilization



Extract throughput results in terms of training examples per second



Determine size of training examples in bytes



Multiply training example throughput and size to estimate training data read bandwidth needed to keep GPUs fully utilized

- MLCommons MLPerf Training benchmark suite ideal for this purpose
- Covers a variety of AI models
- Designed to saturate GPU utilization
- Results from multiple submitters
 publicly available



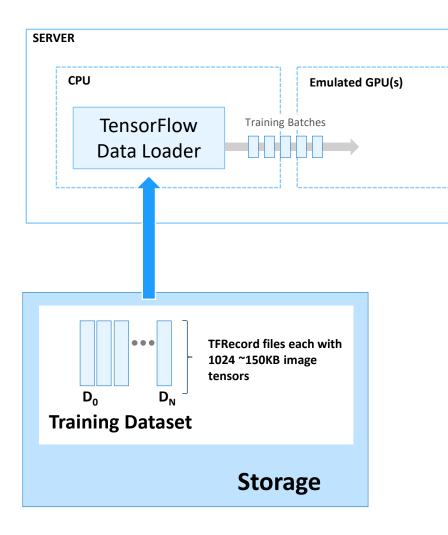
Training data storage read bandwidth requirements vary greatly; depends on model compute boundness and input size

Name	Model Size (Parameters)	Training Dataset	Input Size (Bytes)	# H100 GPUs	Model Throughput (Training Examples/Sec)	Training Data Read Bandwidth	
Resnet-50 Image Classification	23M	ImageNet LSVRC2012 dataset 1.2M images, ~155GB	116K	8	55K	6.1 GB/sec	
BERT-Large Transformer LM	345M	Wikipedia 2020/01/01 dataset, pre-processed to ~86GB	2К	8	5.2K	0.009 GB/sec	
GPT3	175B	C4 dataset, ~305GB	8К	32	19.5K	0.146 GB/sec	Single instance of GPT3 model required 32 GPUs
DLRM- DCNv2 Recommender	24B	Criteo 1TB click-through dataset, synthetically extended, ~ 3.5TB	912	8	12M	10.6 GB/sec	Most of DLRM's parameters are embedding tables, less compute bound than size suggests
3D U-Net 3D Image Segmentation	19M	KiTS19 Kidney Tumor data set 300 3D images, ~27GB	92M	8	463	41.6 GB/sec	-
MaskRCNN Object Detection	44M	COCO data set, 121K images, ~18GB	160K	8	1.3K	0.2 GB/sec	

Based on MLPerf Training v3.0 results for H100 80GB GPUs from multiple submissions



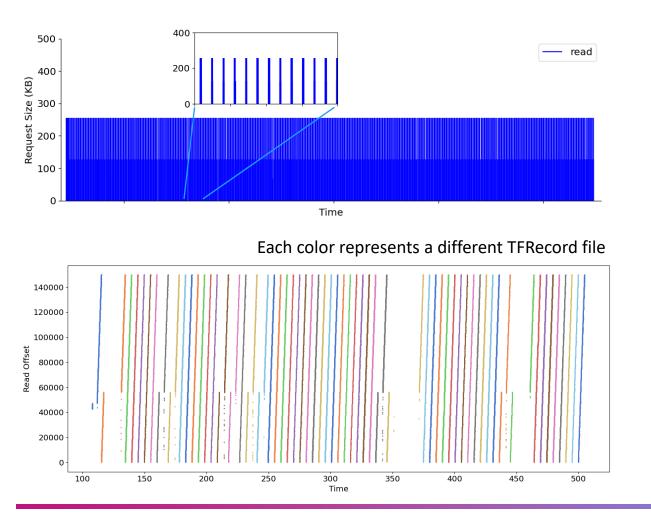
Example: Resnet50 training emulated by DLIO benchmark

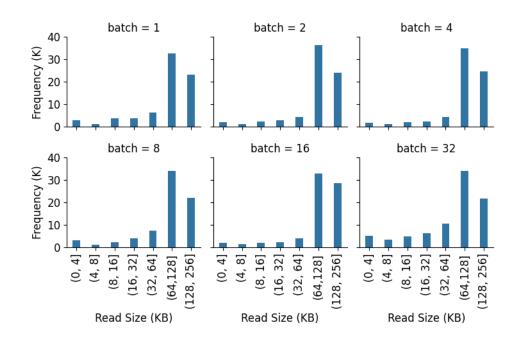


- DLIO modifies TensorFlow Resnet50 implementation to emulate GPUs with a "compute time" delay
- Includes a synthetic data generator that creates TFRecord files with 1024 ~150KB image tensors
- Uses real TensorFlow Data Loader library to access training data
- Produces IO traffic representative of real Resnet50
 training



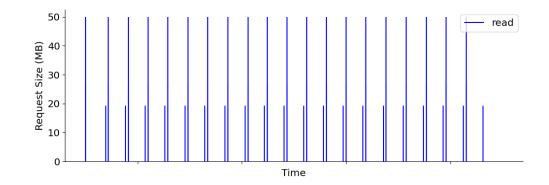
Reading training data via NFS generates a steady stream of sequential 64KB-256KB IOs regardless of batch size





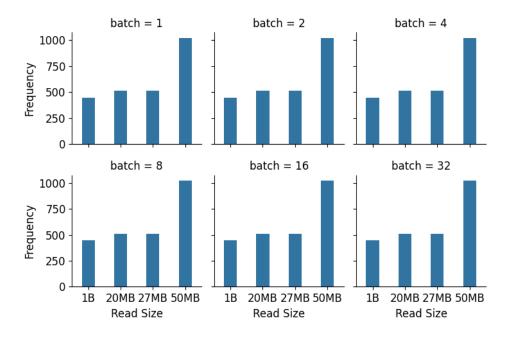


Reading same Resnet50 training data via S3 results in larger sequential 20-50MB IOs



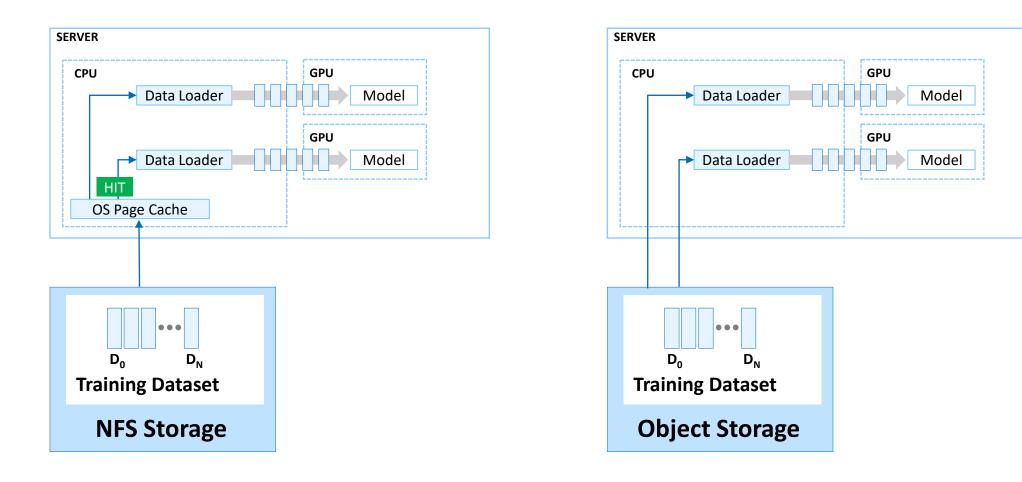
Each color represents a different TFRecord file





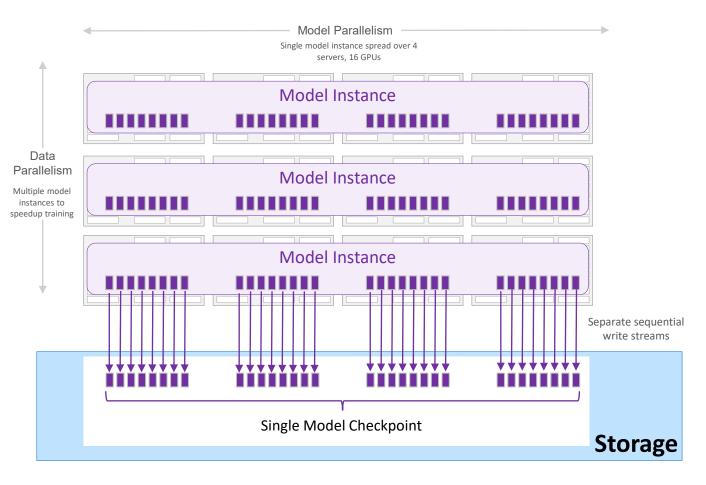


NFS benefits from OS page cache when multiple model instances trained on single server





Checkpoints periodically save training state needed to resume training after a failure or interruption



- Checkpoints contain learned model weights and optimizer state information
- Checkpoints may be saved as one or more files; depends on model parallelism and implementation
- Each checkpoint file is sequentially written by one writer
- For data parallelism, only one model instance needs to be saved; don't need to save all of GPU memory
- Training typically paused during checkpointing reducing GPU utilization, important to complete quickly



Checkpoint aggregate write bandwidth requirements depend on model size and maximum allowed time

Model	Checkpoint	Total Write BW (GBps) Needed to Checkpoint within Time Lim				
Parameters	Size	72 sec	180 sec	360 sec	540 sec	720 sec
(B)	(GB)	(1% 2Hrs)	(2.5% 2Hrs)	(5% 2Hrs)	(7.5% 2Hrs)	(10% 2Hrs)
3	42	0.6	0.2	0.1	0.1	0.1
7	98	1.4	0.5	0.3	0.2	0.1
13	182	2.5	1.0	0.5	0.3	0.3
33	462	6.4	2.6	1.3	0.9	0.6
70	980	13.6	5.4	2.7	1.8	1.4
140	1960	27.2	10.9	5.4	3.6	2.7
175	2450	34.0	13.6	6.8	4.5	3.4
530	7420	103.1	41.2	20.6	13.7	10.3

Assumptions:

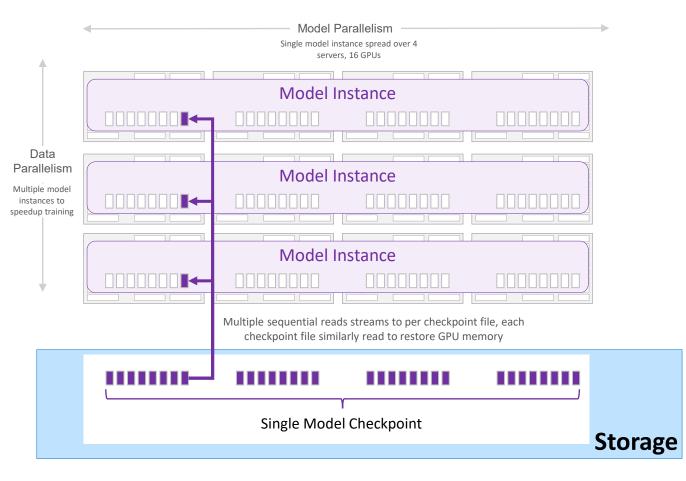
• Checkpoints every 2 hours

• 2 bytes per model parameter (BF16)

• 12 bytes per model parameter for optimizer and other state



Resuming from a checkpoint requires restoring saved state to all GPUs



- Each GPU's memory must be re-initialized with weights and optimizer state from appropriate checkpoint file(s)
- Checkpoint files typically read sequentially
- When using model parallelism, a single checkpoint file may be used to restore multiple GPUs
- Number of readers per checkpoint file depends on degree of data parallelism
- Training unable to start until all GPU memory restored

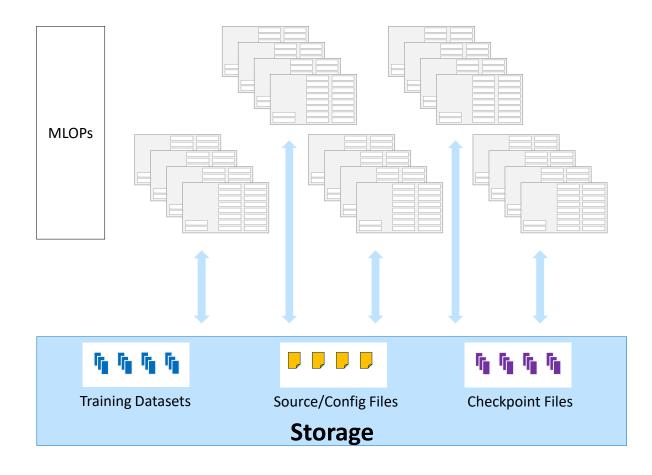


Checkpoint aggregate read BW depends on model size, data parallelism, and maximum allowed time

Model	Checkpoint	Total Read BW (GBps) Needed to Restore Checkpoint within 5 Minutes					Minutes
Parameters	Size	# Model Instances (Data Parallelism)					
(B)	(GB)	1	8	16	32	64	128
3	42	0.002	0.02	0.04	0.07	0.15	0.30
7	98	0.01	0.04	0.09	0.17	0.35	0.70
13	182	0.01	0.08	0.16	0.32	0.65	1.29
33	462	0.03	0.21	0.41	0.82	1.64	3.29
70	980	0.05	0.44	0.87	1.74	3.48	6.97
140	1960	0.11	0.87	1.74	3.48	6.97	13.94
175	2450	0.14	1.09	2.18	4.36	8.71	17.42
530	7420	0.41	3.30	6.60	13.19	26.38	52.76



GPU clusters run multiple workloads, rely on equal access to data, and require scalable storage performance & capacity



- Modern GPU clusters may contain thousands of servers and 10's of thousands of GPUs
- MLOPs platforms with distributed scheduling used to assign and execute jobs across cluster
- Jobs need access to training, checkpoint, and other data regardless of server deployed on
- Likely many simultaneous storage workloads including data prep, training, and checkpointing
- GPU clusters expected to grow as business demands increase, storage must scale accordingly



Al storage required to perform and scale across Al lifecycle

	Requirements & Considerations					
Reading Training Data	 Accommodate wide range of read BW requirements and IO access patterns across different AI models Deliver large amounts of read BW to single GPU servers for most demanding models 	 Use high performance, all-flash storage to meet needs Leverage RDMA capable storage protocols, when possible, for most demanding requirements 				
Saving Checkpoints	 Provide large sequential write bandwidth for quickly saving checkpoints Handle multiple large sequential write streams to separate files, especially in same directory 	 Understand checkpoint implementation details and behaviors for expected AI workloads Determine time limits for completing checkpoints 				
Restoring Checkpoints	 Provide large sequential read bandwidth for quickly restoring checkpoints Handle multiple large sequential read streams to same checkpoint file 	 Understand how often checkpoint restoration will be required Determine acceptable time limits for restoration 				
Servicing GPU Clusters	 Meet performance requirements for mixed storage workloads from multiple simultaneous AI jobs Scale capacity and performance as GPU clusters grow with business needs 	 Consider scale-out storage platforms that can increase performance and capacity while providing shared access to data 				



Also consider traditional enterprise storage requirements still applicable to Al

- Data protection
- High availability
- Compression and deduplication
- At rest encryption
- Multi-protocol data access
- Remote and hybrid cloud replication
- Security and governance
- Long term archival storage
- Data lifecycle management



THANK YOU

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