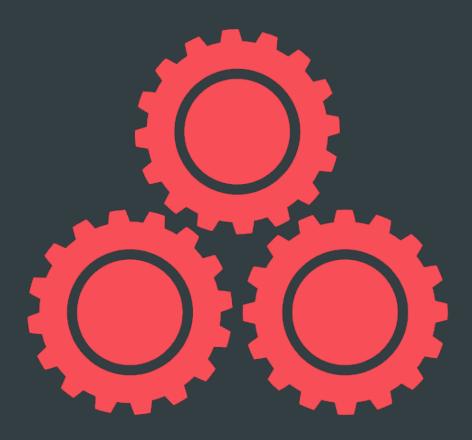


ERASURE CODING AND CACHE TIERING

SAGE WEIL - SDC 2014.09.16



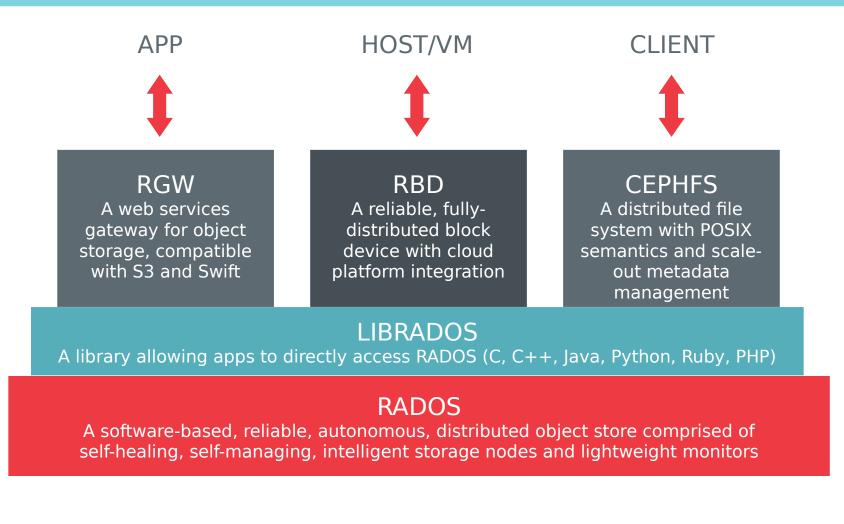
ARCHITECTURE

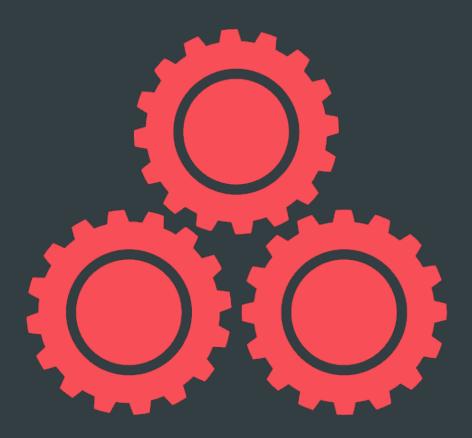
CEPH MOTIVATING PRINCIPLES



- All components must scale horizontally
- There can be no single point of failure
- The solution must be hardware agnostic
- Should use commodity hardware
- Self-manage whenever possible
- Open source

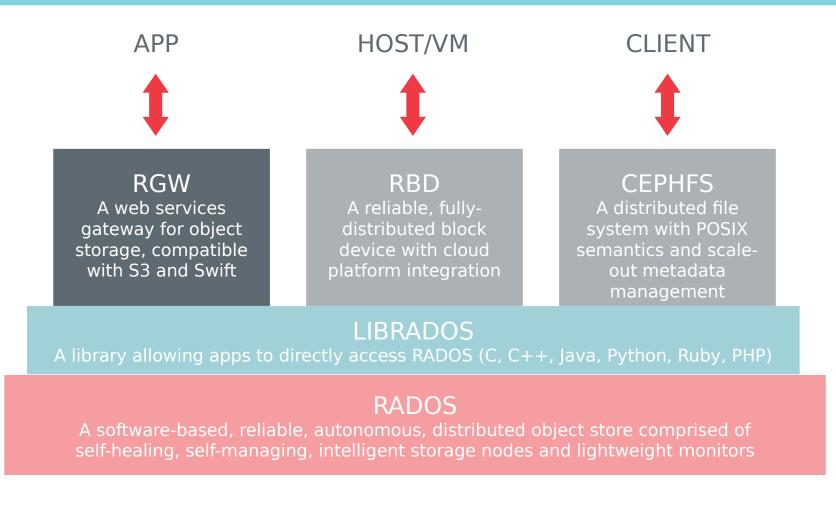
ARCHITECTURAL COMPONENTS





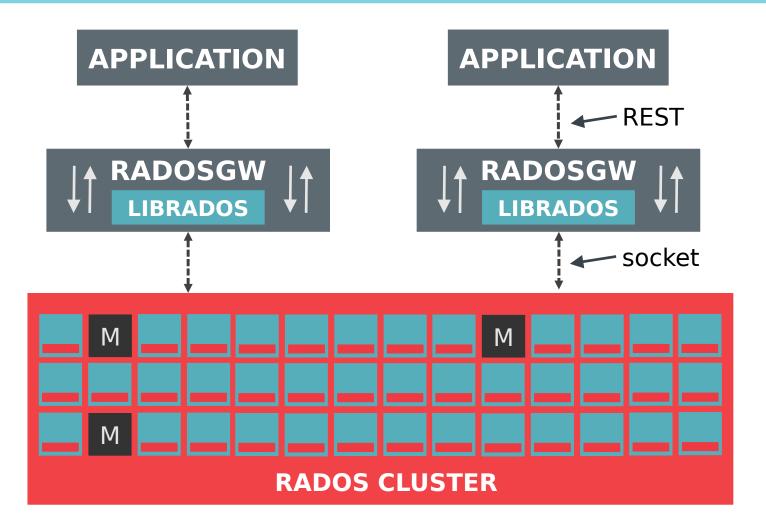
ROBUST SERVICES BUILT ON RADOS

ARCHITECTURAL COMPONENTS



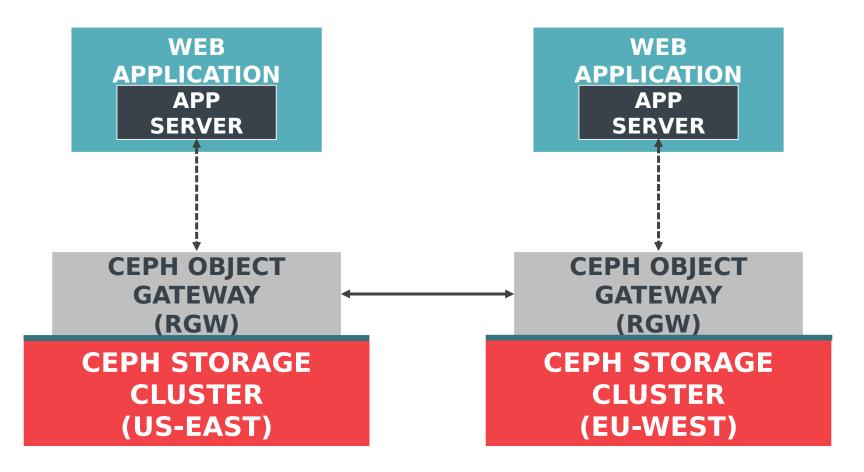
THE RADOS GATEWAY





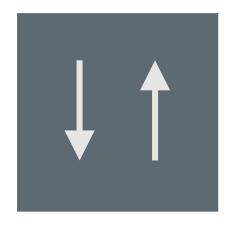
MULTI-SITE OBJECT STORAGE





RADOSGW MAKES RADOS WEBBY

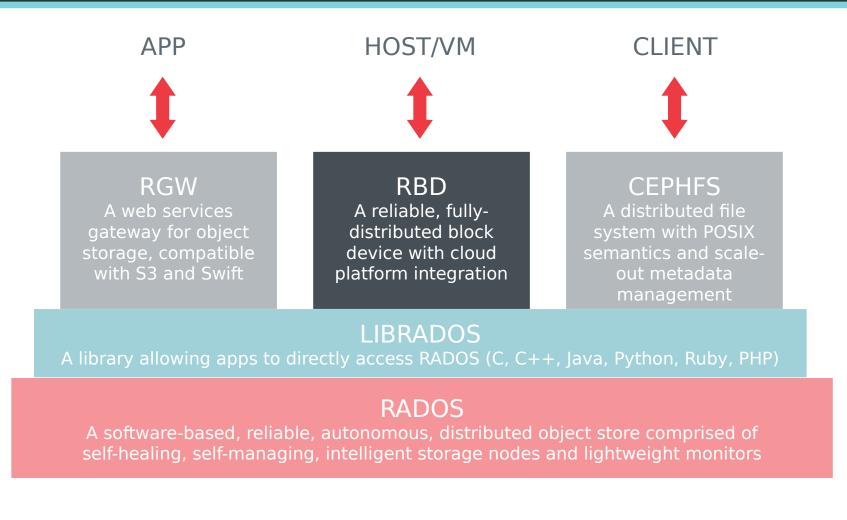




RADOSGW:

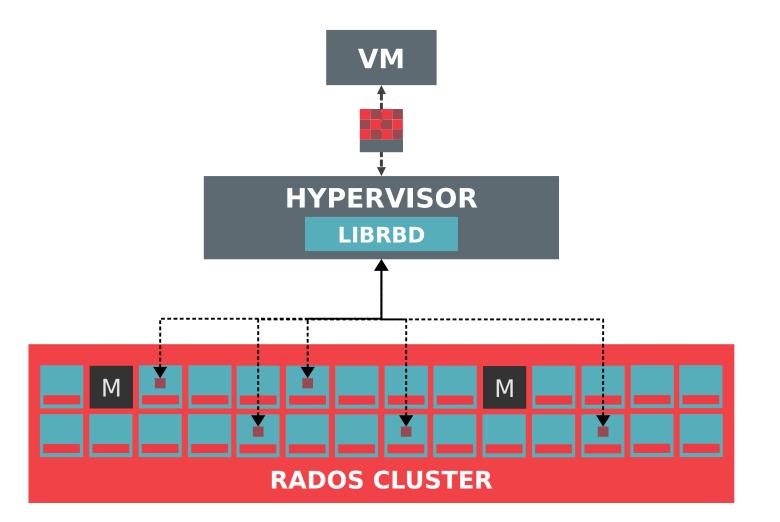
- REST-based object storage proxy
- Uses RADOS to store objects
 - Stripes large RESTful objects across many RADOS objects
- API supports buckets, accounts
- Usage accounting for billing
- Compatible with S3 and Swift applications

ARCHITECTURAL COMPONENTS



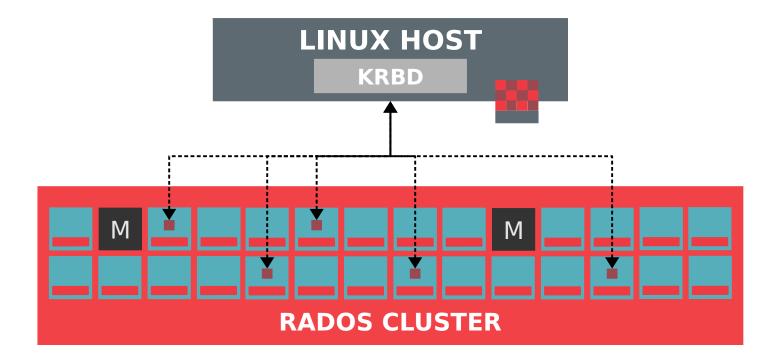
STORING VIRTUAL DISKS





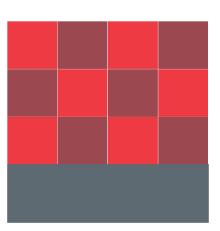
KERNEL MODULE





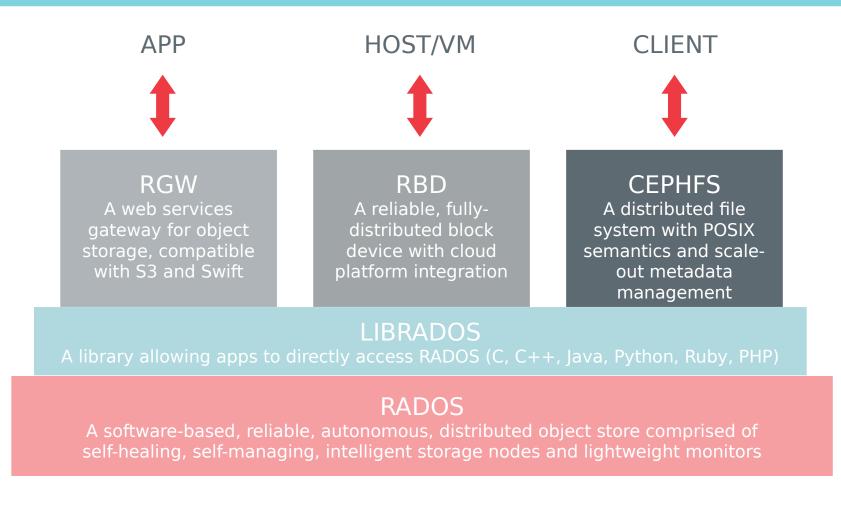
RBD FEATURES

- Stripe images across entire cluster (pool)
- Read-only snapshots
- Copy-on-write clones
- Broad integration
 - Qemu
 - Linux kernel
 - iSCSI (STGT, LIO)
 - OpenStack, CloudStack, Nebula, Ganeti, Proxmox
- Incremental backup (relative to snapshots)



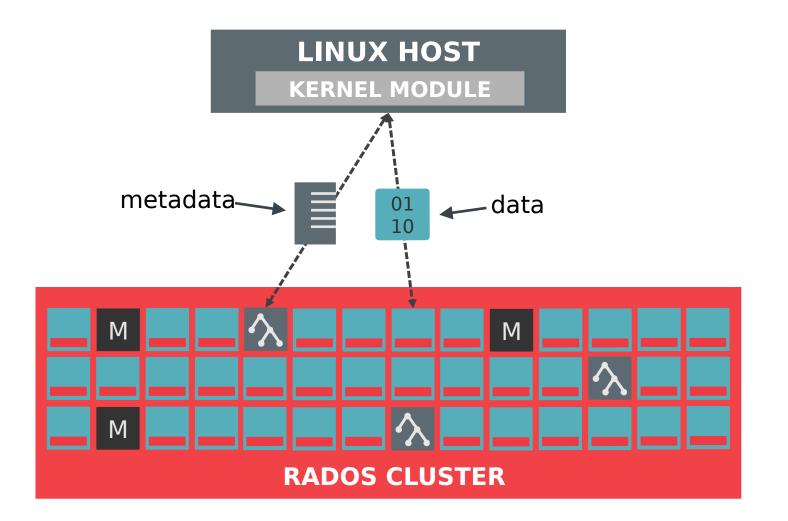


ARCHITECTURAL COMPONENTS



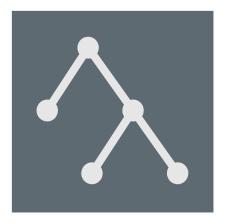
SEPARATE METADATA SERVER





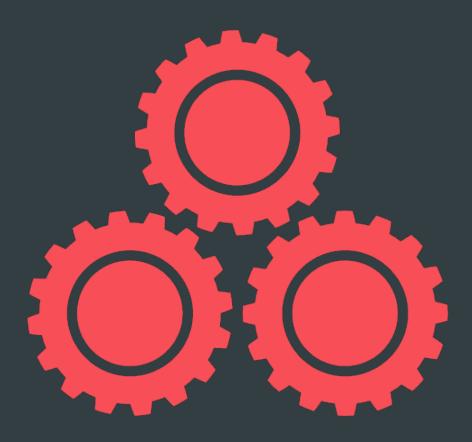
SCALABLE METADATA SERVERS





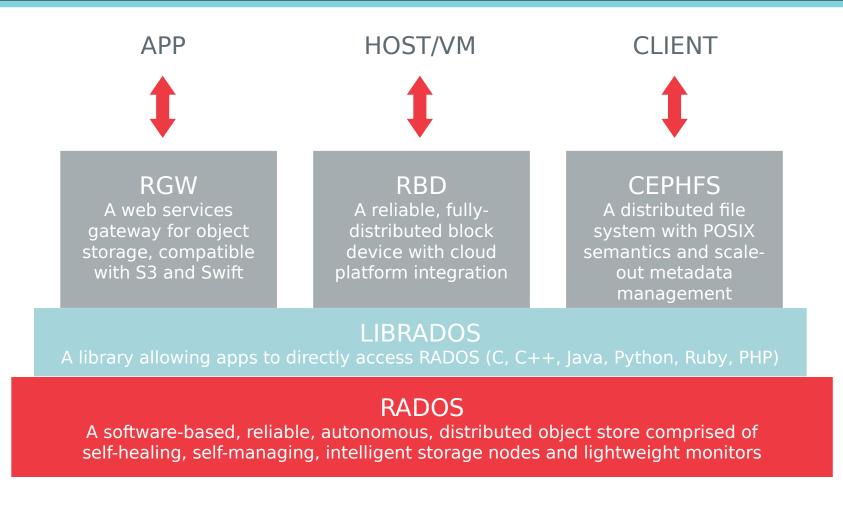
METADATA SERVER

- Manages metadata for a POSIX-compliant shared filesystem
 - Directory hierarchy
 - File metadata (owner, timestamps, mode, etc.)
- Clients stripe file data in RADOS
 - MDS not in data path
- MDS stores metadata in RADOS
 - Key/value objects
- Dynamic cluster scales to 10s or 100s
- Only required for shared filesystem





ARCHITECTURAL COMPONENTS



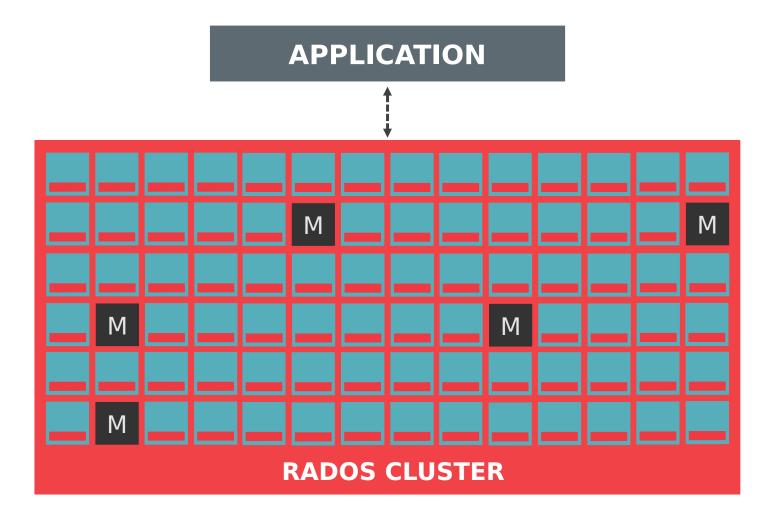
RADOS

- Flat object namespace within each pool
- Rich object API (librados)
 - Bytes, attributes, key/value data
 - Partial overwrite of existing data
 - Single-object compound operations
 - RADOS classes (stored procedures)
- Strong consistency (CP system)
- Infrastructure aware, dynamic topology
- Hash-based placement (CRUSH)
- Direct client to server data path



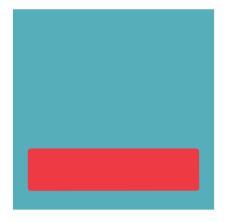
RADOS CLUSTER





RADOS COMPONENTS





OSDs:

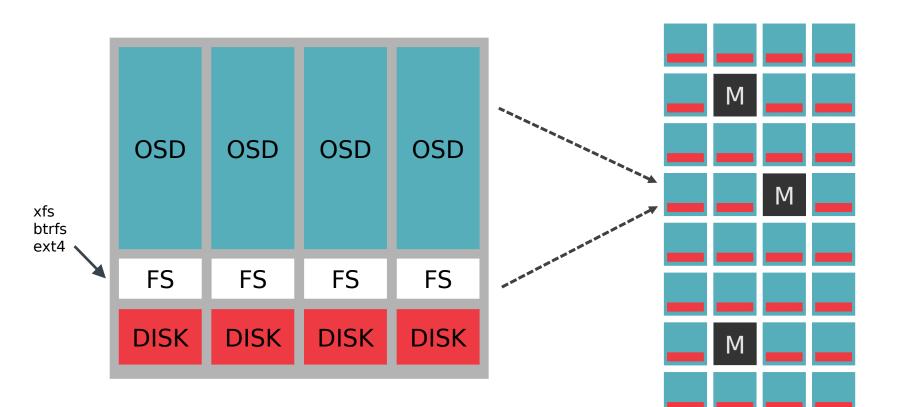
- 10s to 1000s in a cluster
- One per disk (or one per SSD, RAID group...)
- Serve stored objects to clients
- Intelligently peer for replication & recovery

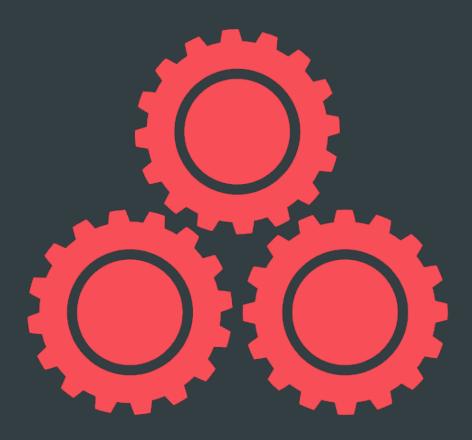


Monitors:

- Maintain cluster membership and state
- Provide consensus for distributed decisionmaking
- Small, odd number (e.g., 5)
- Not part of data path

OBJECT STORAGE DAEMONS

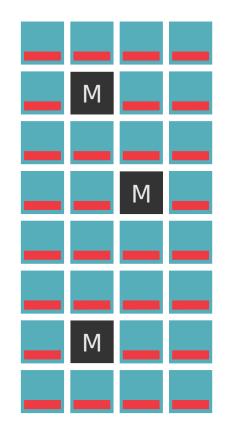




DATA PLACEMENT

WHERE DO OBJECTS LIVE?

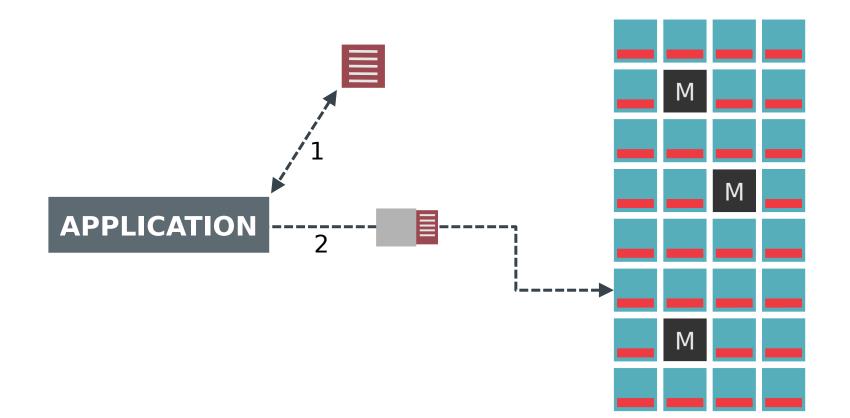






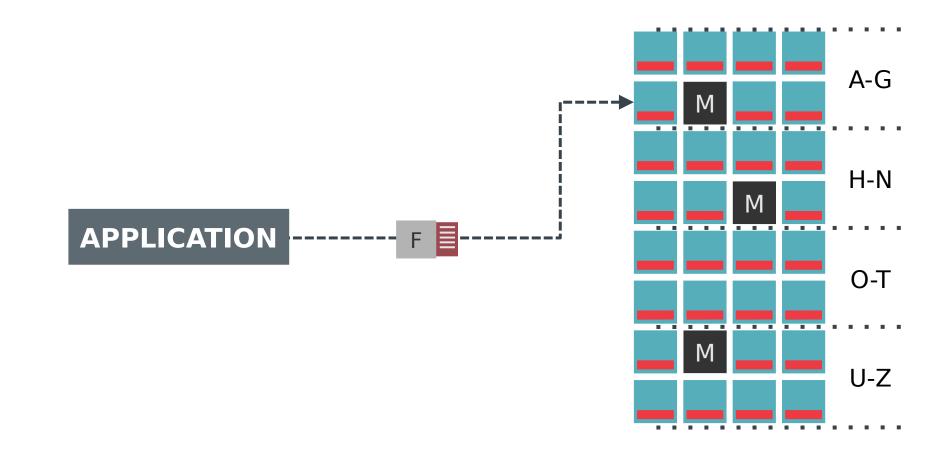
A METADATA SERVER?





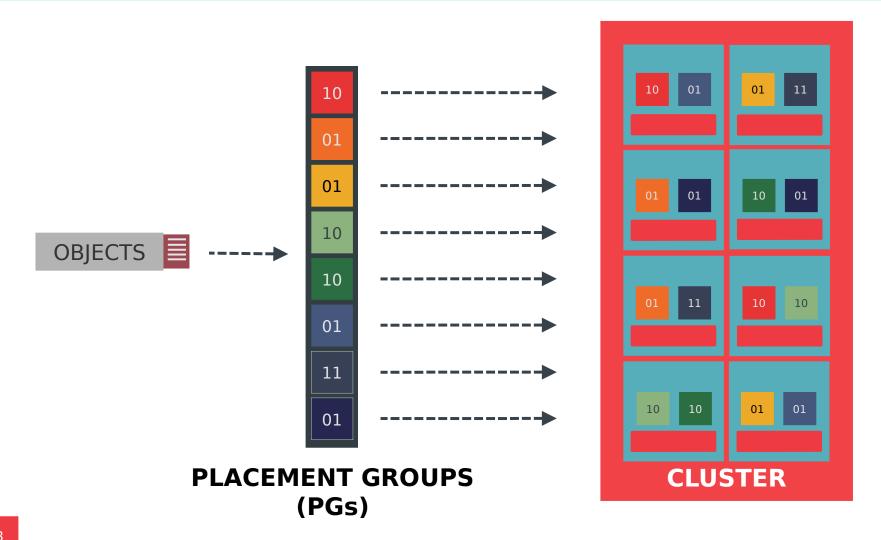
CALCULATED PLACEMENT



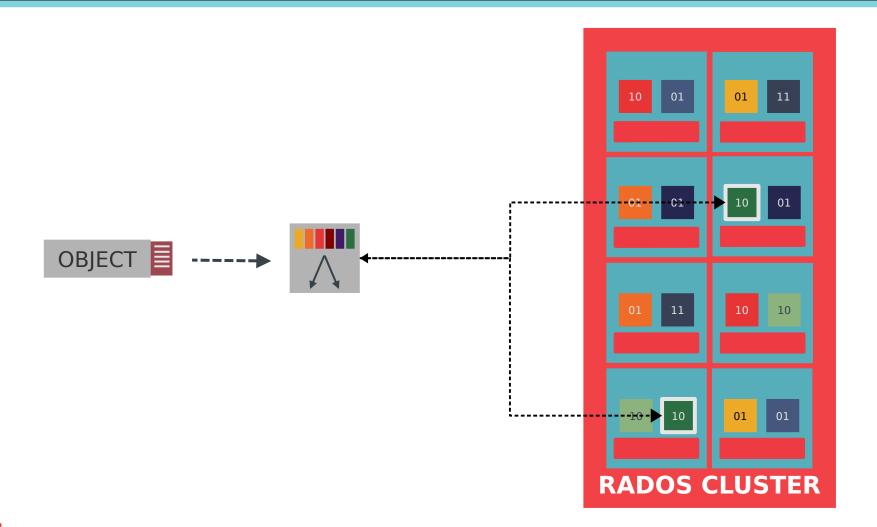


CRUSH

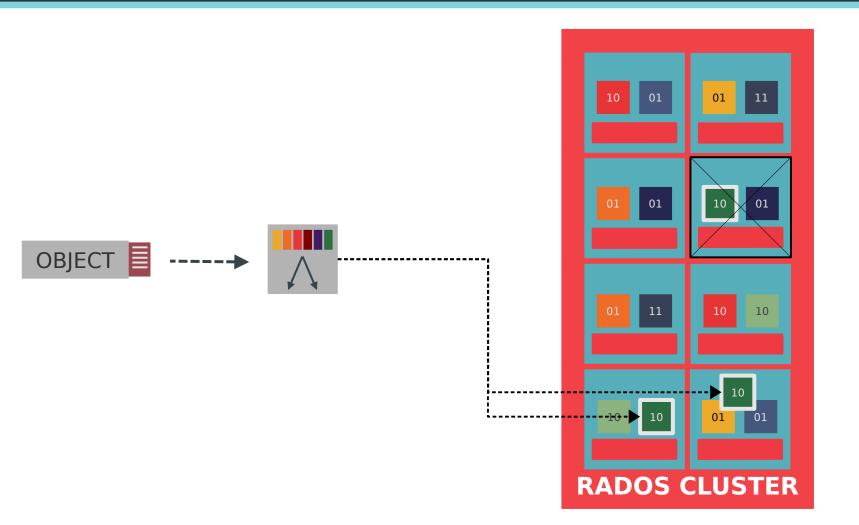




CRUSH IS A QUICK CALCULATION



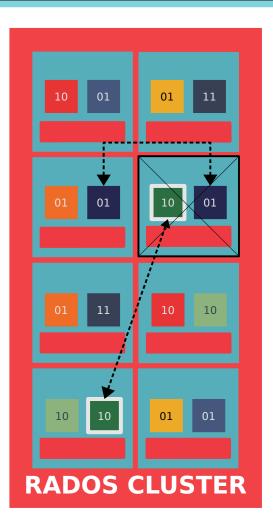
CRUSH AVOIDS FAILED DEVICES



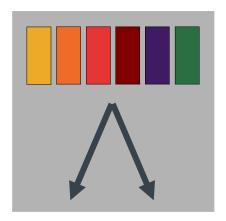
CRUSH: DECLUSTERED PLACEMENT

 \bigcirc

- Each PG independently maps to a pseudorandom set of OSDs
- PGs that map to the same OSD generally have replicas that do not
- When an OSD fails, each PG it stored will generally be re-replicated by a different OSD
 - Highly parallel recovery



CRUSH: DYNAMIC DATA PLACEMENT

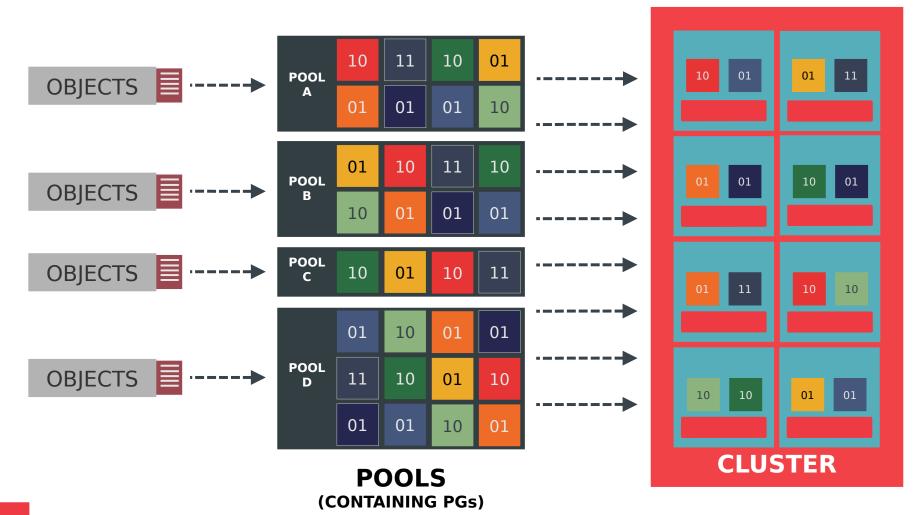


CRUSH:

- Pseudo-random placement algorithm
 - Fast calculation, no lookup
 - Repeatable, deterministic
- Statistically uniform distribution
- Stable mapping
 - Limited data migration on change
- Rule-based configuration
 - Infrastructure topology aware
 - Adjustable replication
 - Weighting

DATA IS ORGANIZED INTO POOLS





33



TIERED STORAGE

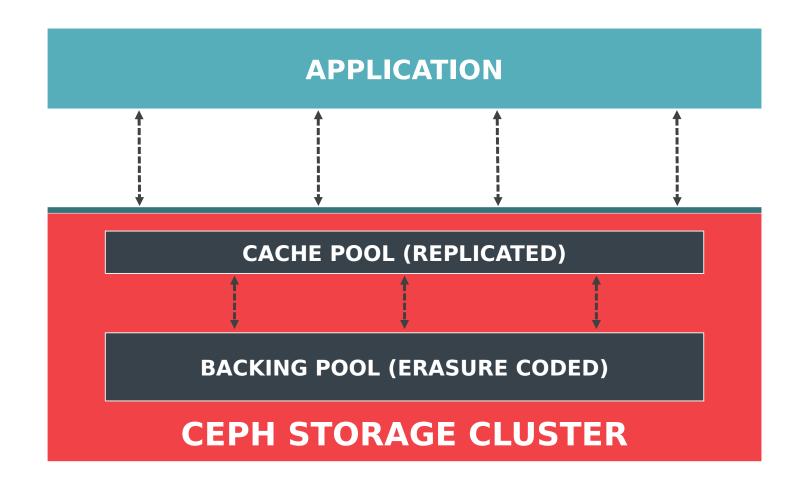
TWO WAYS TO CACHE



- Within each OSD
 - Combine SSD and HDD for each OSD
 - Make localized promote/demote decisions
 - Leverage existing tools
 - dm-cache, bcache, FlashCache
 - Variety of caching controllers
 - We can help with hints
- Cache on separate devices/nodes
 - Different hardware for different tiers
 - Slow nodes for cold data
 - High performance nodes for hot data
 - Add, remove, scale each tier independently
 - Unlikely to choose right ratios at procurement time

TIERED STORAGE





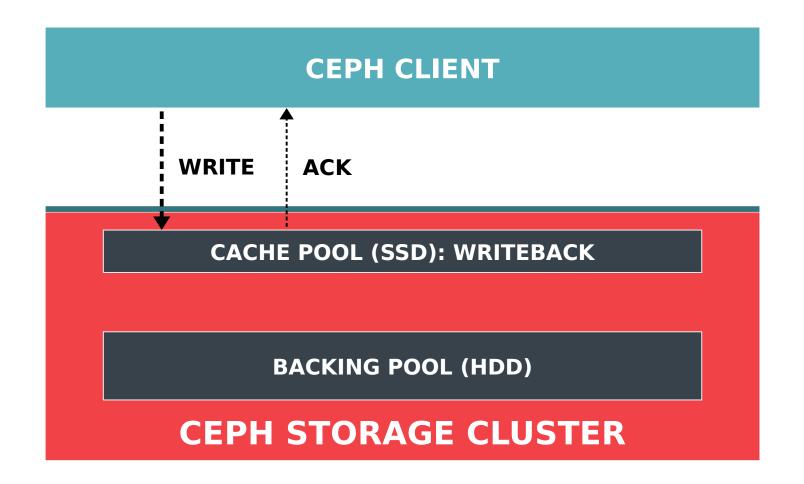
RADOS TIERING PRINCIPLES



- Each tier is a RADOS pool
 - May be replicated or erasure coded
- Tiers are durable
 - e.g., replicate across SSDs in multiple hosts
- Each tier has its own CRUSH policy
 - e.g., map to SSDs devices/hosts only
- librados clients adapt to tiering topology
 - Transparently direct requests accordingly
 - e.g., to cache
 - No changes to RBD, RGW, CephFS, etc.

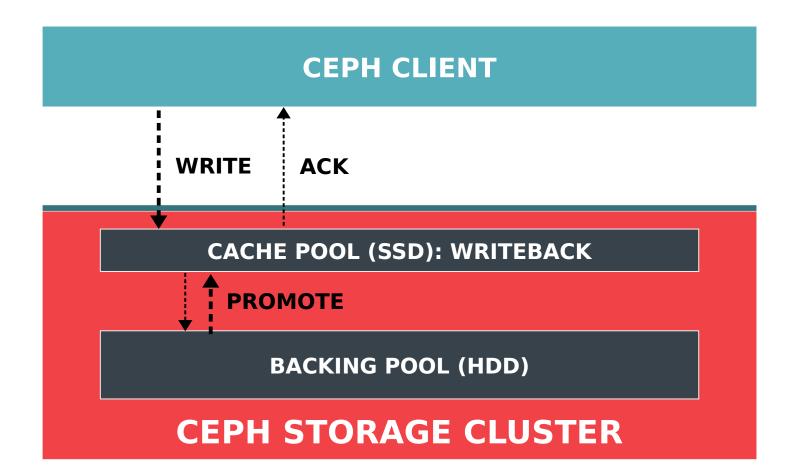
WRITE INTO CACHE POOL





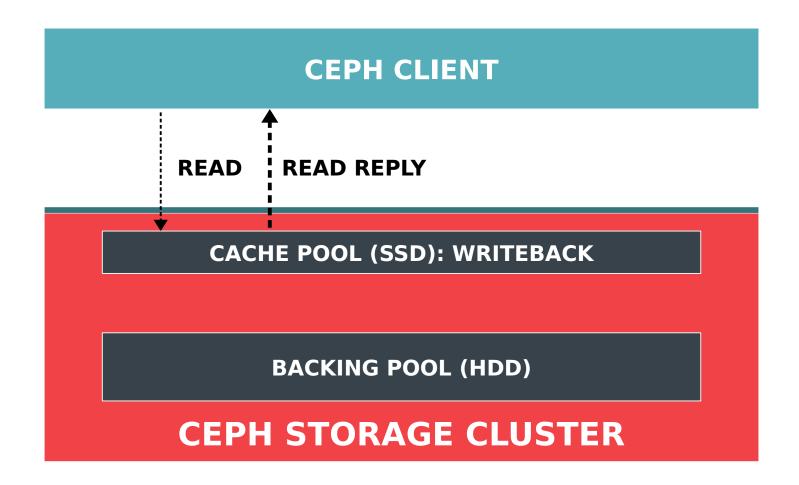
WRITE INTO CACHE POOL





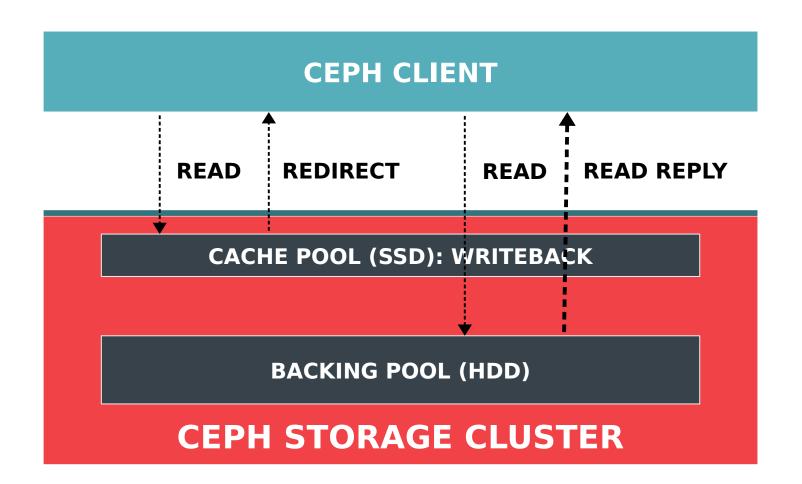
READ (CACHE HIT)





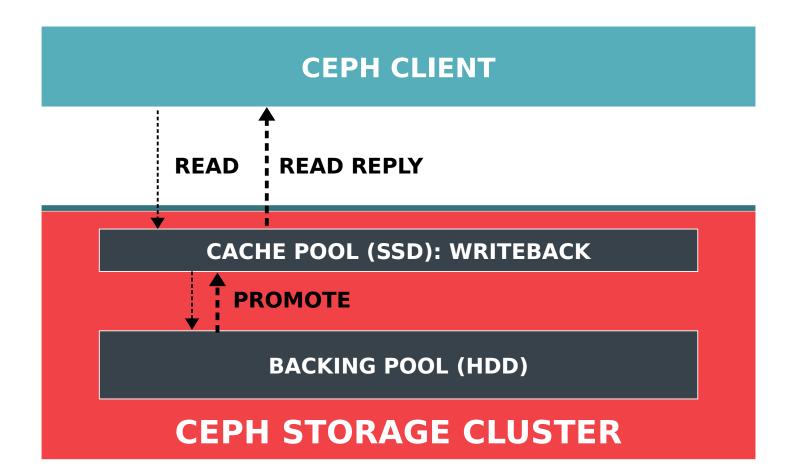
READ (CACHE MISS)





READ (CACHE MISS)





ESTIMATING TEMPERATURE

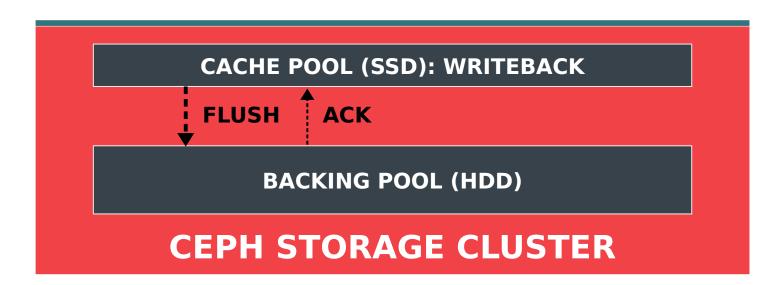


- Each PG constructs in-memory bloom filters
 - Insert records on both read and write
 - Each filter covers configurable period (e.g., 1 hour)
 - Tunable false positive probability (e.g., 5%)
 - Maintain most recent N filters on disk
- Estimate temperature
 - Has object been accessed in any of the last N periods?
 - ...in how many of them?
 - Informs flush/evict decision
- Estimate "recency"
 - How many periods since the object hasn't been accessed?
 - Informs read miss behavior: promote vs redirect

AGENT: FLUSH COLD DATA



CEPH CLIENT



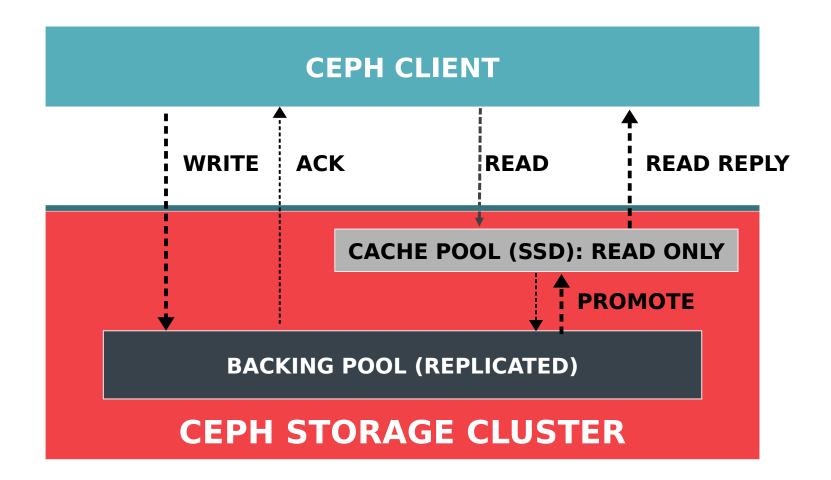
TIERING AGENT



- Each PG has an internal tiering **agent**
 - Manages PG based on administrator defined policy
- Flush **dirty** objects
 - When pool reaches target dirty ratio
 - Tries to select cold objects
 - Marks objects clean when they have been written back to the base pool
- Evict clean objects
 - Greater "effort" as pool/PG size approaches target size

READ ONLY CACHE TIER



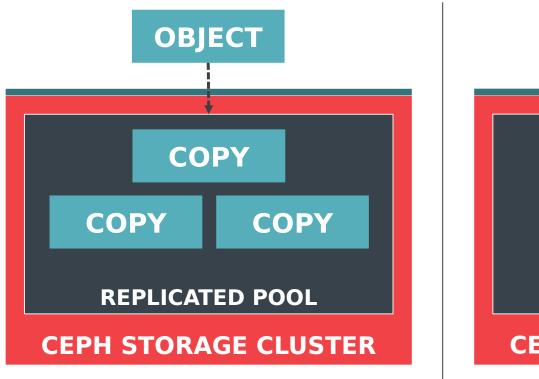




ERASURE CODING

ERASURE CODING

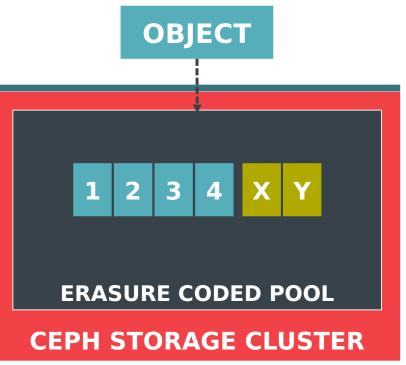




Full copies of stored objects

- Very high durability
- 3x (200% overhead)
- Quicker recovery

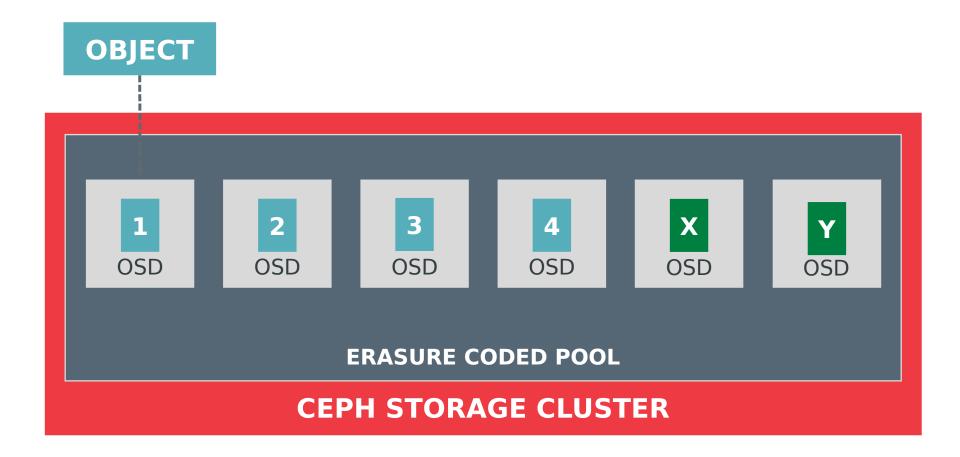
48



One copy plus parity

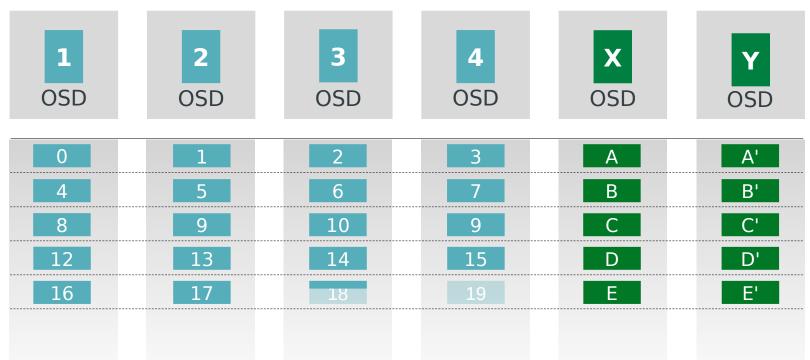
- Cost-effective durability
- 1.5x (50% overhead)
- Expensive recovery

ERASURE CODING SHARDS



ERASURE CODING SHARDS

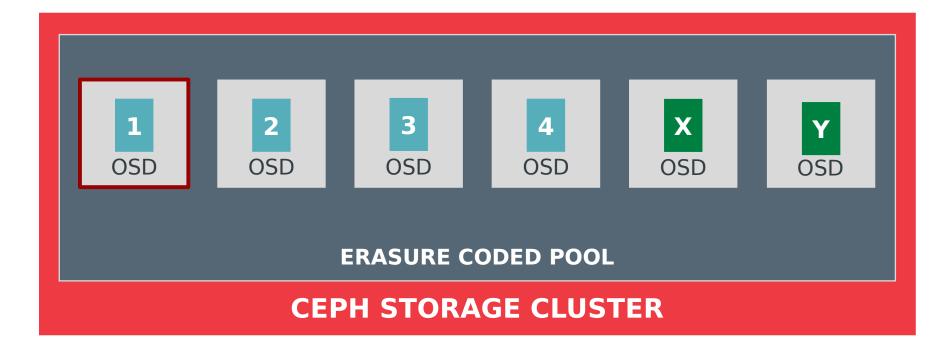




- Variable stripe size
- Zero-fill shards (logically) in partial tail stripe

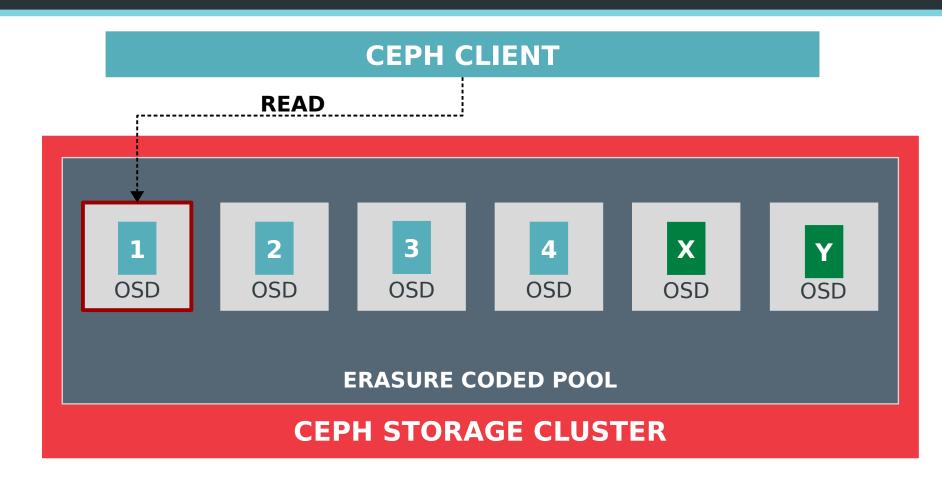
PRIMARY





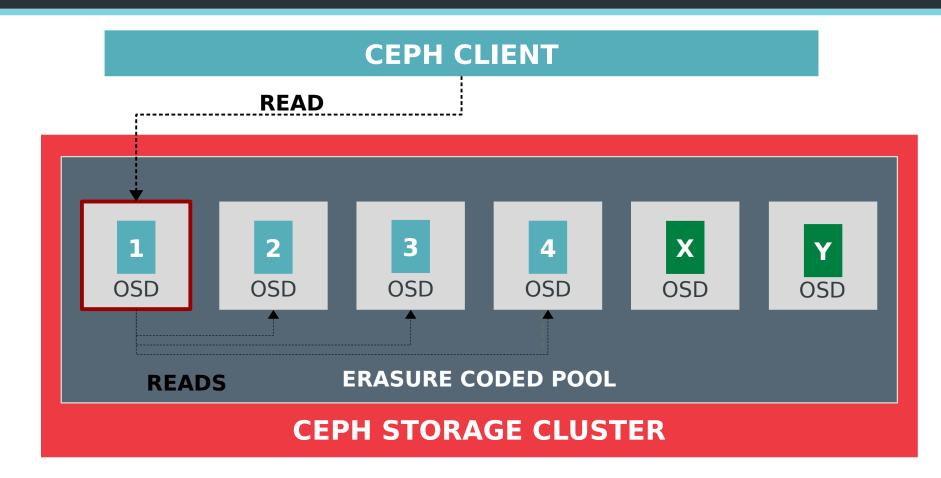
EC READ





EC READ





CEPH CLIENT

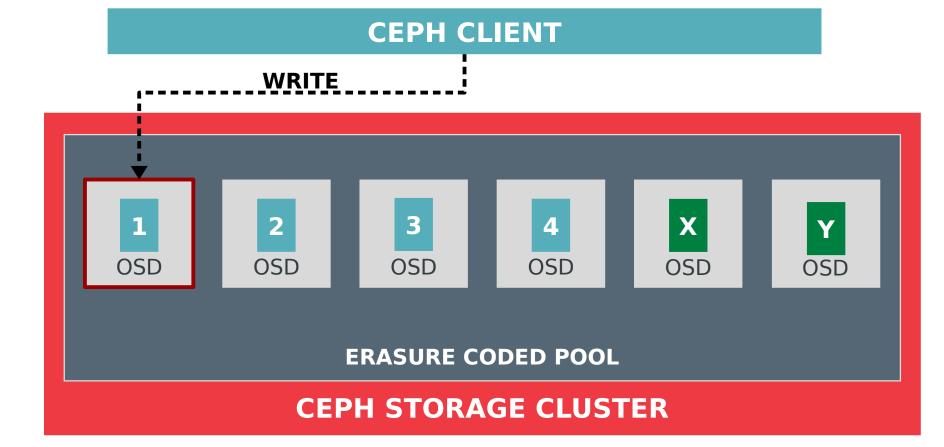
1 2 3 4 X Y Y OSD OSD OSD OSD OSD OSD OSD OSD OSD ERASURE CODED POOL F</t

CEPH STORAGE CLUSTER



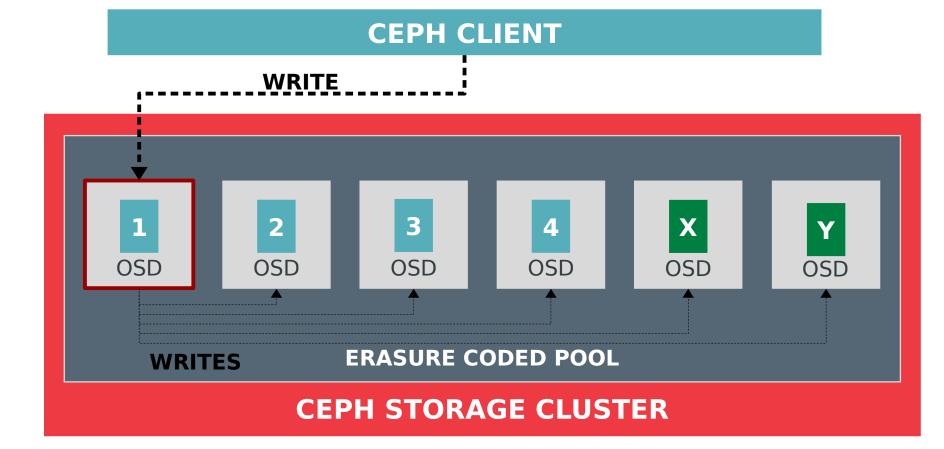


EC WRITE



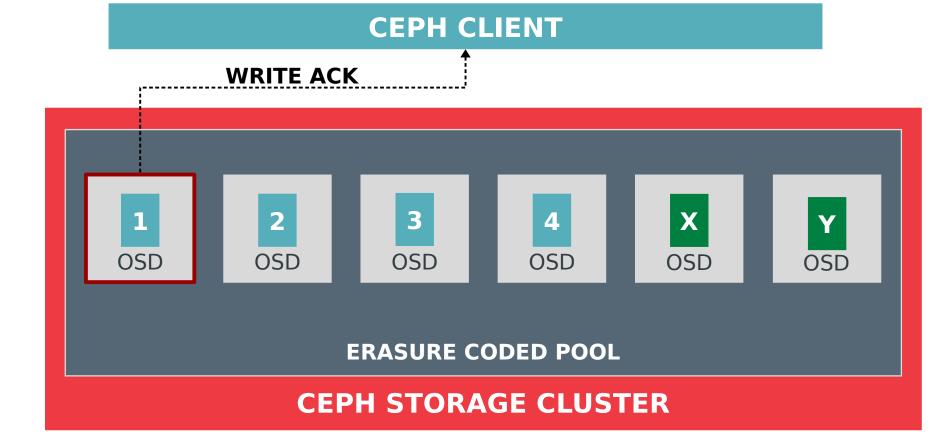


EC WRITE





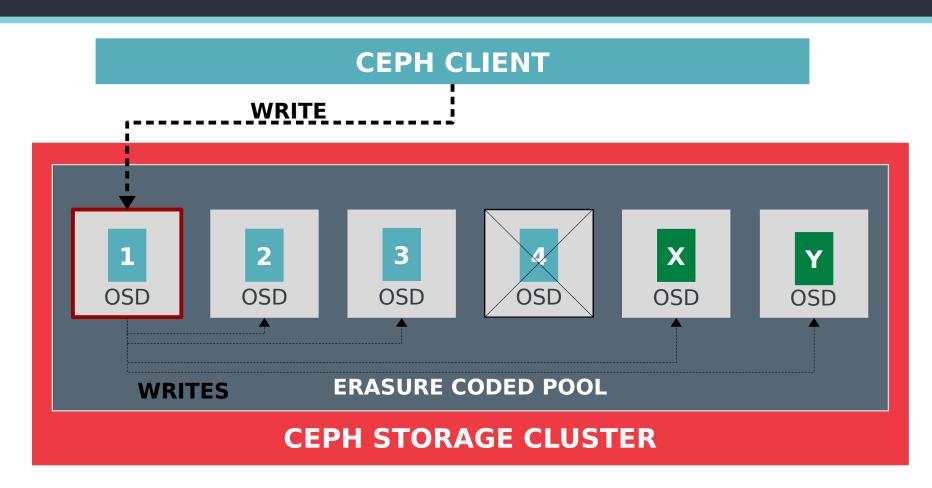
EC WRITE





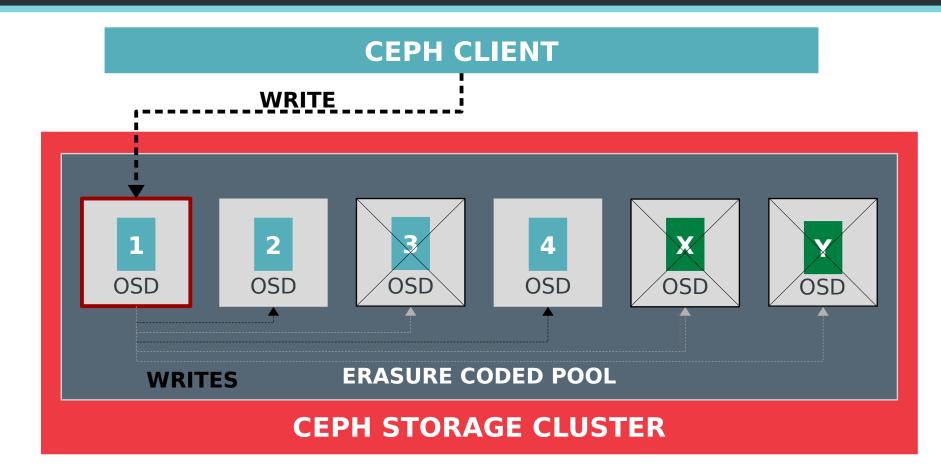
EC WRITE: DEGRADED





EC WRITE: PARTIAL FAILURE

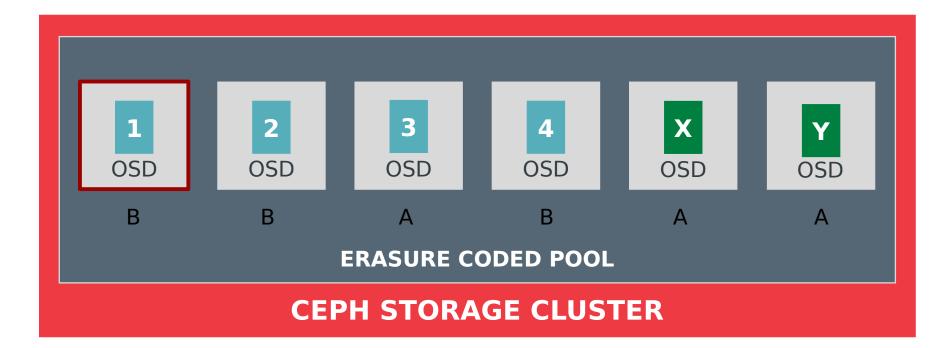




EC WRITE: PARTIAL FAILURE



CEPH CLIENT



EC RESTRICTIONS

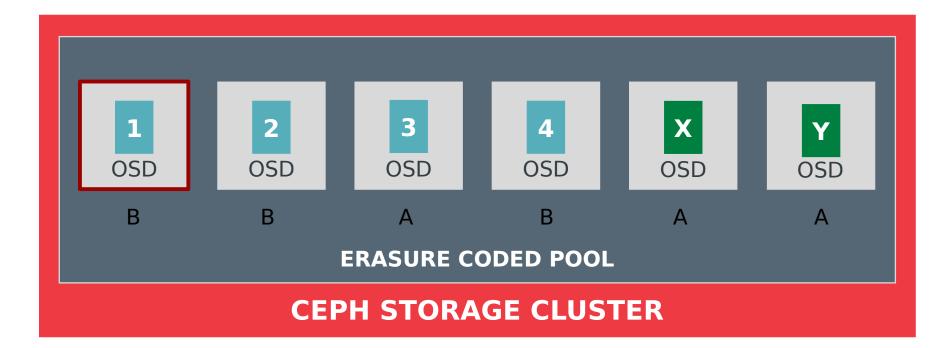


- Overwrite in place will not work in general
- Log and 2PC would increase complexity, latency
- We chose to restrict allowed operations
 - create
 - append (on stripe boundary)
 - remove (keep previous generation of object for some time)
- These operations can all easily be rolled back locally
 - create → delete
 - append → truncate
 - remove → roll back to previous generation
- Object attrs preserved in existing PG logs (they are small)
- Key/value data is not allowed on EC pools

EC WRITE: PARTIAL FAILURE



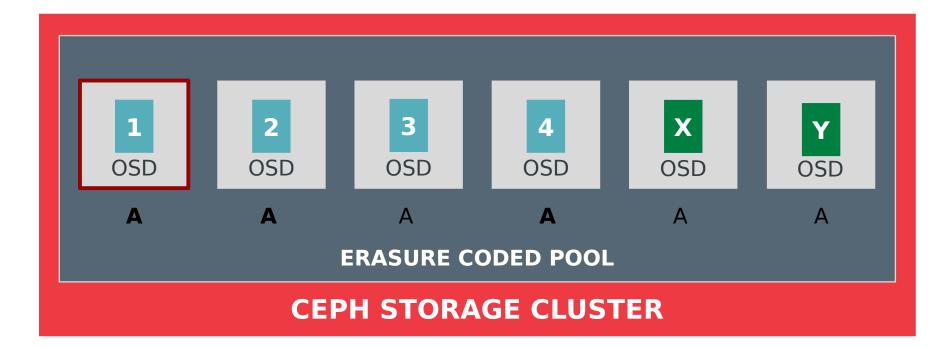
CEPH CLIENT



EC WRITE: PARTIAL FAILURE



CEPH CLIENT



EC RESTRICTIONS



- This is a small subset of allowed librados operations
 - Notably cannot (over)write any extent
- Coincidentally, these operations are also inefficient for erasure codes
 - Generally require read/modify/write of affected stripe(s)
- Some applications can consume EC directly
 - RGW (no object data update in place)
- Others can combine EC with a cache tier (RBD, CephFS)
 - Replication for warm/hot data
 - Erasure coding for cold data
 - Tiering agent skips objects with key/value data

WHICH ERASURE CODE?



- The EC algorithm and implementation are pluggable
 - jerasure (free, open, and very fast)
 - ISA-L (Intel library; optimized for modern Intel procs)
 - LRC (local recovery code layers over existing plugins)
- Parameterized
 - Pick k or m, stripe size
- OSD handles data path, placement, rollback, etc.
- Plugin handles
 - Encode and decode
 - Given these available shards, which ones should I fetch to satisfy a read?
 - Given these available shards and these missing shards, which ones should I fetch to recover?

COST OF RECOVERY





1 TB OSD

COST OF RECOVERY





1 TB OSD

COST OF RECOVERY (REPLICATION)



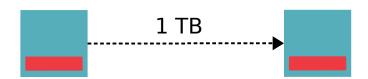
1 TB

COST OF RECOVERY (REPLICATION)



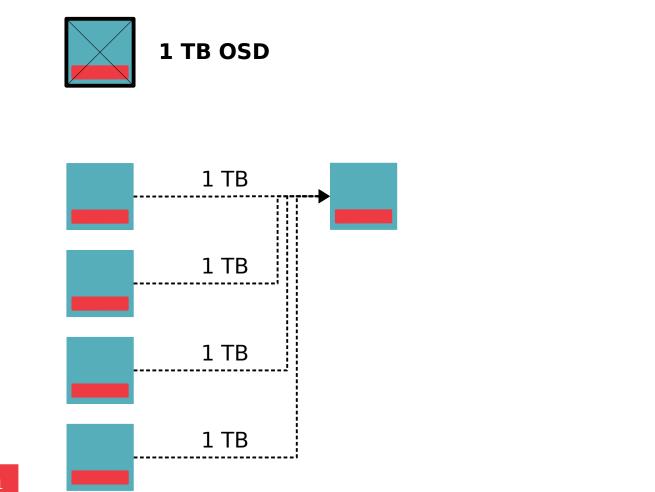
COST OF RECOVERY (REPLICATION)



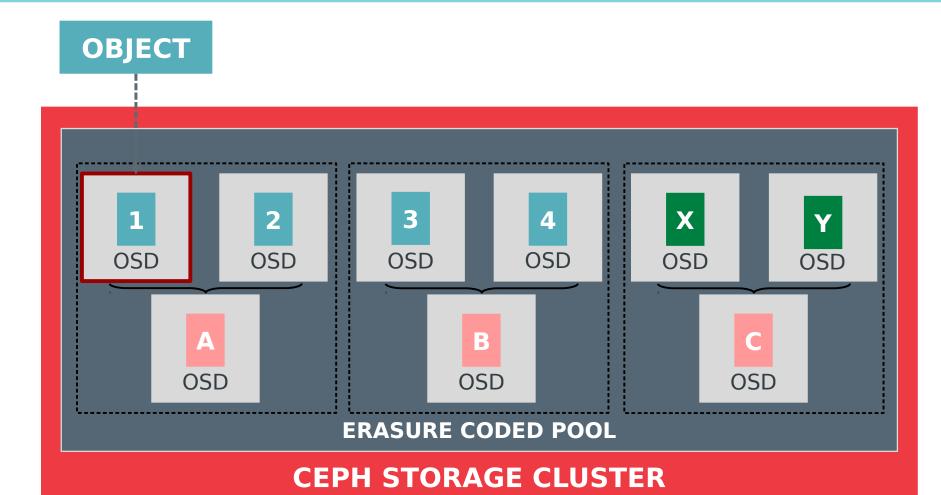


COST OF RECOVERY (EC)





LOCAL RECOVERY CODE (LRC)



BIG THANKS TO



- Ceph
 - Loic Dachary (CloudWatt, FSF France, Red Hat)
 - Andreas Peters (CERN)
 - Sam Just (Inktank / Red Hat)
 - David Zafman (Inktank / Red Hat)
- jerasure
 - Jim Plank (University of Tennessee)
 - Kevin Greenan (Box)





WHAT'S NEXT



- Erasure coding
 - Allow (optimistic) client reads directly from shards
 - ARM optimizations for jerasure
- Cache pools
 - Better agent decisions (when to flush or evict)
 - Supporting different performance profiles
 - e.g., slow / "cheap" flash can read just as fast
 - Complex topologies
 - Multiple readonly cache tiers in multiple sites
- Tiering
 - Support "redirects" to cold tier below base pool
 - Dynamic spin-down

OTHER ONGOING WORK



- Performance optimization (SanDisk, Mellanox)
- Alternative OSD backends
 - leveldb, rocksdb, LMDB
 - hybrid key/value and file system
- Messenger (network layer) improvements
 - RDMA support (libxio Mellanox)
 - Event-driven TCP implementation (UnitedStack)
- Multi-datacenter RADOS replication
- CephFS
 - Online consistency checking
 - Performance, robustness

THANK YOU!

Sage Weil CEPH PRINCIPAL ARCHITECT



sage@redhat.com



